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Riadh Zaier

Build Your Own Paper Robots Julius Perdana,Josh Buczynski,Kurt Young,2009-08-18 Presents projects, instructions, and color templates for fourteen paper robots.

Biologically Inspired Robotics Yunhui Liu,Dong Sun,2011-12-21 Robotic engineering inspired by biology—biomimetics—has many potential applications: robot snakes can be used for rescue operations in disasters, snake-like endoscopes can be used in medical diagnosis, and artificial muscles can replace damaged muscles to recover the motor functions of human limbs. Conversely, the application of robotics technology to our understanding of biological systems and behaviors—biorobotic modeling and analysis—provides unique research opportunities: robotic manipulation technology with optical tweezers can be used to study the cell mechanics of human red blood cells, a surface electromyography sensing system can help us identify the relation between muscle forces and hand movements, and mathematical models of brain circuitry may help us understand how the cerebellum achieves movement control. Biologically Inspired Robotics contains cutting-edge material—considerably expanded and with additional analysis—from the 2009 IEEE International Conference on Robotics and Biomimetics (ROBIO). These 16 chapters cover both biomimetics and biorobotic modeling/analysis, taking readers through an exploration of biologically inspired robot design and control, micro/nano bio-robotic systems, biological measurement and actuation, and applications of robotics technology to biological problems. Contributors examine a wide range of topics, including: A method for controlling the motion of a robotic snake The design of a bionic fitness cycle inspired by the jaguar The use of autonomous robotic fish to detect pollution A noninvasive brain-activity scanning method using a hybrid sensor A rehabilitation system for recovering motor function in human hands after injury Human-like robotic eye and head movements in human-machine interactions A state-of-the-art resource for graduate students and researchers in the fields of control engineering, robotics, and biomedical engineering, this text helps readers understand the technology and principles in this emerging field.

Template Matching Techniques in Computer Vision Roberto Brunelli,2009-04-29 The detection and recognition of objects in images is a key research topic in the computer vision community. Within this area, face recognition and interpretation has attracted increasing attention owing to the possibility of unveiling human perception mechanisms, and for the development of practical biometric systems. This book and the accompanying website, focus on template matching, a subset of object recognition techniques of wide applicability, which has proved to be particularly effective for face recognition applications. Using examples from face processing tasks throughout the book to illustrate more general object recognition approaches, Roberto Brunelli: examines the basics of digital image formation, highlighting points critical to the task of template matching; presents basic and advanced template matching techniques, targeting grey-level images, shapes and point sets; discusses recent pattern classification paradigms from a template matching perspective; illustrates the development of a real face recognition system; explores the use of advanced computer graphics techniques in the development of computer vision algorithms. Template Matching Techniques in Computer Vision is primarily aimed at practitioners working on the development of systems for effective object recognition such as biometrics, robot navigation, multimedia retrieval and landmark detection. It is also of interest to graduate students undertaking studies in these areas.

Advanced Mechanics in Robotic Systems Nestor Eduardo Nava Rodríguez,2011-07-22 Humans have always been fascinated with the concept of artificial life and the construction of machines that look and behave like people. As the field of robotics evolves, it demands continuous development of successful systems with high-performance characteristics for practical applications. Advanced Mechanics in Robotic Systems illustrates original and ambitious mechanical designs and techniques for developing new robot prototypes with successful mechanical operational skills. Case studies are focused on projects in mechatronics that have high growth expectations: humanoid robots, robotics hands, mobile robots, parallel manipulators, and human-centred robots. A good control strategy requires good mechanical design, so a chapter has also been devoted to the description of suitable methods for control architecture design. Readers of Advanced Mechanics in Robotic Systems will discover novel designs for relevant applications in robotic fields, that will be of particular interest to academic and industry-based researchers.

Robot Manipulation of Deformable Objects Dominik Henrich,Heinz Wörn,2012-12-06 This book is about automatic handling of non-rigid or deformable objects like cables, fabric, or foam rubber. The automation by robots in industrial environments, is especially examined. It discusses several important automation aspects, such as material modelling and simulation, planning and control strategies, collaborative systems, and industrial applications. This book collects contributions from various countries and international projects and, therefore, provides a representative overview of the state of the art in this field. It is of particular interest for scientists and practitioners in the area of robotics and automation

Beginning Django Daniel Rubio,2017-10-27 Discover the Django web application framework and get started building Python-based web applications. This book takes you from the basics of Django all the way through to cutting-edge topics such as creating RESTful applications. Beginning Django also covers ancillary, but essential, development topics, including configuration settings, static resource management, logging, debugging, and email. Along with material on data access with SQL queries, you'll have all you need to get up and running with Django 1.11 LTS, which is compatible with Python 2 and Python 3. Once you've built your web application, you'll need to be the admin, so the next part of the book covers how to enforce permission management with users and groups. This technique allows you to restrict access to URLs and content, giving you total control of your data. In addition, you'll work with and customize the Django admin site, which provides access to a Django project's data. After reading and using this book, you'll be able to build a Django application top to bottom and be ready to move on to more advanced or complex Django application development. What You'll Learn Get started with the Django framework Use Django views, class-based views, URLs, middleware, forms, templates, and Jinja templates Take advantage of Django models, including model relationships, migrations, queries, and forms Leverage the Django admin site to get access to the database used by a Django project Deploy Django REST services to serve as the data backbone for mobile, IoT, and SaaS systems Who This Book Is For Python developers new to the Django web application development framework and web developers new to Python and Django.

The Everything Store Brad Stone,2013-10-15 The authoritative account of the rise of Amazon and its intensely driven founder, Jeff Bezos, praised by the Seattle Times as the definitive account of how a tech icon came to life. Amazon.com started off delivering books through the mail. But its visionary founder, Jeff Bezos, wasn't content with being a bookseller. He wanted Amazon to become the everything store, offering limitless selection and seductive convenience at disruptively low prices. To do so, he developed a corporate culture of relentless ambition and secrecy that's never been cracked. Until now. Brad Stone enjoyed unprecedented access to current and former Amazon employees and Bezos family members, giving readers the first in-depth, fly-on-the-wall account of life at Amazon. Compared to tech's other elite innovators -- Jobs, Gates, Zuckerberg -- Bezos is a private man. But he stands out for his restless pursuit of new markets, leading Amazon into risky new ventures like the Kindle and cloud computing, and transforming retail in the same way Henry Ford revolutionized manufacturing. The Everything Store is the revealing, definitive biography of the company that placed one of the first and largest bets on the Internet and forever changed the way we shop and read.

The Future of Humanoid Robots Riadh Zaier,2012-01-20 This book provides state of the art scientific and engineering research findings and developments in the field of humanoid robotics and its applications. It is expected that humanoids will change the way we interact with machines, and will have the ability to blend perfectly into an environment already designed for humans. The book contains chapters that aim to discover the future abilities of humanoid robots by presenting a variety of integrated research in various scientific and engineering fields, such as locomotion, perception, adaptive behavior, human-robot interaction, neuroscience and machine learning. The book is designed to be accessible and practical, with an emphasis on useful information to those working in the fields of robotics, cognitive science, artificial intelligence, computational methods and other fields of science directly or indirectly related to the development and usage of future humanoid robots. The editor of the book has extensive R

Robots, Artificial Intelligence and Service Automation in Travel, Tourism and Hospitality Stanislav Ivanov,Craig Webster,2019-10-14 Using a combination of theoretical discussion and real-world case studies, this book focuses on current and future use of RAISA technologies in the tourism economy, including examples from the hotel, restaurant, travel agency, museum, and events industries.

Web 2.0 Miltiadis D. Lytras,Ernesto Damiani,Patricia Ordóñez de Pablos,2008-10-20 While the web itself is about twenty years old, businesses

are still implementing the technology into the fabric of the business model. The background section will focus on defining the building blocks for the framework including defining the basic components of Web 1.0 which focused on the presence and business transaction. The Web 2.0 section will focus on defining the basic building blocks of customer interactions, while the final section will focus on a review of the wine industry.

2.1 Web 1.0: Presence and Electronic Commerce The term Web 1.0 emerged from the research around the development of Web 2.0. Prior to this, researchers commonly referred to Web 1.0 as Electronic Commerce or E-Business. Whereas, web 1.0 focused on a read-only web interface, Web 2.0 focuses on a read-write interface where value emerges from the contribution of a large volume of users. The Internet initially focused on the command and control of the information itself. Information was controlled by a relatively small number of resources but distributed to a large number which spawned the massive growth of the web itself. Like television before it, the web allowed for the broadcasting of information to a large number of users. Initial web sites were built simply to communicate presence or provide information on the business itself. This component includes information like marketing materials, investor relations, employment opportunities, and product information.

Essentials of Metaheuristics (Second Edition) Sean Luke, 2012-12-20 Interested in the Genetic Algorithm? Simulated Annealing? Ant Colony Optimization? *Essentials of Metaheuristics* covers these and other metaheuristic algorithms, and is intended for undergraduate students, programmers, and non-experts. The book covers a wide range of algorithms, representations, selection and modification operators, and related topics, and includes 71 figures and 135 algorithms great and small. Algorithms include: Gradient Ascent techniques, Hill-Climbing variants, Simulated Annealing, Tabu Search variants, Iterated Local Search, Evolution Strategies, the Genetic Algorithm, the Steady-State Genetic Algorithm, Differential Evolution, Particle Swarm Optimization, Genetic Programming variants, One- and Two-Population Competitive Coevolution, N-Population Cooperative Coevolution, Implicit Fitness Sharing, Deterministic Crowding, NSGA-II, SPEA2, GRASP, Ant Colony Optimization variants, Guided Local Search, LEM, PBIL, UMDA, cGA, BOA, SAMUEL, ZCS, XCS, and XCSF.

Robot Operating System (ROS) Anis Koubaa, 2017-05-25 This second volume is a continuation of the successful first volume of this Springer book, and as well as addressing broader topics it puts a particular focus on unmanned aerial vehicles (UAVs) with Robot Operating System (ROS). Consisting of three types of chapters: tutorials, cases studies, and research papers, it provides comprehensive additional material on ROS and the aspects of developing robotics systems, algorithms, frameworks, and applications with ROS. ROS is being increasingly integrated in almost all kinds of robots and is becoming the de-facto standard for developing applications and systems for robotics. Although the research community is actively developing applications with ROS and extending its features, amount of literature references is not representative of the huge amount of work being done. The book includes 19 chapters organized into six parts: Part 1 presents the control of UAVs with ROS, while in Part 2, three chapters deal with control of mobile robots. Part 3 provides recent work toward integrating ROS with Internet, cloud and distributed systems. Part 4 offers five case studies of service robots and field experiments. Part 5 presents signal-processing tools for perception and sensing, and lastly, Part 6 introduces advanced simulation frameworks. The diversity of topics in the book makes it a unique and valuable reference resource for ROS users, researchers, learners and developers.

Artificial Cilia Jaap M.J. den Toonder, Patrick R. Onck, 2013-05-31 Cilia are tiny hairs covering biological cells to generate and sense fluid flow. Millions of years of evolution have inspired a novel technology which is barely a decade old. Artificial cilia have been developed to control and sense fluid flow in microscopic systems, presenting new and interesting options for flow control in lab-on-a-chip devices. This appealing link between nature and technology has seen rapid development in the last few years, and this book presents a review of the state-of-the-art in the form of a professional reference book. The editors have pioneered the field, having initiated a major European project on this topic soon after its inception. Active researchers in academia and industry will benefit from the comprehensive nature of this book, while postgraduates and those new to the field will gain a clear understanding of the theory, techniques and applications of artificial cilia.

Introduction to Information Systems R. Kelly Rainer, Efraim Turban, 2008-01-09 WHAT'S IN IT FOR ME? Information technology lives all around us—in how we communicate, how we do business, how we shop, and how we learn. Smart phones, iPods, PDAs, and wireless devices dominate our lives, and yet it's all too easy for students to take information technology for granted. Rainer and Turban's *Introduction to Information Systems*, 2nd edition helps make Information Technology come alive in the classroom. This text takes students where IT lives—in today's businesses and in our daily lives while helping students understand how valuable information technology is to their future careers. The new edition provides concise and accessible coverage of core IT topics while connecting these topics to Accounting, Finance, Marketing, Management, Human resources, and Operations, so students can discover how critical IT is to each functional area and every business. Also available with this edition is WileyPLUS—a powerful online tool that provides instructors and students with an integrated suite of teaching and learning resources in one easy-to-use website. The WileyPLUS course for *Introduction to Information Systems*, 2nd edition includes animated tutorials in Microsoft Office 2007, with iPod content and podcasts of chapter summaries provided by author Kelly Rainer.

Entrepreneurship Marc J. Dollinger, 1999 New to Prentice Hall, this upper-level Entrepreneurship text is perfect for the MBA or Executive MBA market. Brief, paperback, the text frames the theories and applications of entrepreneurship within a resource-based theory focus. The new edition is designed to be more user-friendly, with increased pedagogy, (such as the Street Stories mini-cases.)

World Development Report 2019 World Bank, 2018-10-31 Work is constantly reshaped by technological progress. New ways of production are adopted, markets expand, and societies evolve. But some changes provoke more attention than others, in part due to the vast uncertainty involved in making predictions about the future. The 2019 World Development Report will study how the nature of work is changing as a result of advances in technology today. Technological progress disrupts existing systems. A new social contract is needed to smooth the transition and guard against rising inequality. Significant investments in human capital throughout a person's lifecycle are vital to this effort. If workers are to stay competitive against machines they need to train or retool existing skills. A social protection system that includes a minimum basic level of protection for workers and citizens can complement new forms of employment. Improved private sector policies to encourage startup activity and competition can help countries compete in the digital age. Governments also need to ensure that firms pay their fair share of taxes, in part to fund this new social contract. The 2019 World Development Report presents an analysis of these issues based upon the available evidence.

Artificial Intelligence and Games Georgios N. Yannakakis, Julian Togelius, 2018-02-17 This is the first textbook dedicated to explaining how artificial intelligence (AI) techniques can be used in and for games. After introductory chapters that explain the background and key techniques in AI and games, the authors explain how to use AI to play games, to generate content for games and to model players. The book will be suitable for undergraduate and graduate courses in games, artificial intelligence, design, human-computer interaction, and computational intelligence, and also for self-study by industrial game developers and practitioners. The authors have developed a website (<http://www.gameaibook.org>) that complements the material covered in the book with up-to-date exercises, lecture slides and reading.

Free-to-Play Will Luton, 2013-05-27 “Will's knowledge of F2P comes from years of building games, as well as writing about and consulting with developers on the model. All the topics covered in this book—economics, gameplay, monetization, analytics and marketing—are important to consider when you're building an F2P game, and Will covers each with an easy-to-digest style.” —Ian Marsh, co-founder, NimbleBit *Free-to-Play: Making Money From Games You Give Away* is an accessible and complete guide to the business model that has revolutionized the videogames industry, creating huge hits, multi-billion-dollar startups and a new deal for players: Play for free, spend on what you like. Written by respected game designer and consultant Will Luton, *Free-to-Play* gives you the in-the-trenches insight you need to build, run and make money from games you give away. In it you'll find: Psychology behind player decisions and the motivations to play Simple and accessible explanations of the math and economic theories behind F2P, including working examples Processes for capturing and using player data to improve your game Marketing tips on positioning your game and attracting players Plus: A downloadable F2P spreadsheet, articles from the author, a foreword by NimbleBit co-founder Ian Marsh and an interview with Zynga CEO, Mark Pincus.

Soft Robotics: Trends, Applications and Challenges Cecilia Laschi, Jonathan Rossiter, Fumiya Iida, Matteo Cianchetti, Laura Margheri, 2016-09-21

This book offers a comprehensive, timely snapshot of current research, technologies and applications of soft robotics. The different chapters, written by international experts across multiple fields of soft robotics, cover innovative systems and technologies for soft robot legged locomotion, soft robot manipulation, underwater soft robotics, biomimetic soft robotic platforms, plant-inspired soft robots, flying soft robots, soft robotics in surgery, as well as methods for their modeling and control. Based on the results of the second edition of the Soft Robotics Week, held on April 25 – 30, 2016, in Livorno, Italy, the book reports on the major research lines and novel technologies presented and discussed during the event.

Autonomy and Artificial Intelligence: A Threat or Savior? W.F. Lawless,Ranjeev Mittu,Donald Sofge,Stephen Russell,2017-08-24 This book explores how Artificial Intelligence (AI), by leading to an increase in the autonomy of machines and robots, is offering opportunities for an expanded but uncertain impact on society by humans, machines, and robots. To help readers better understand the relationships between AI, autonomy, humans and machines that will help society reduce human errors in the use of advanced technologies (e.g., airplanes, trains, cars), this edited volume presents a wide selection of the underlying theories, computational models, experimental methods, and field applications. While other literature deals with these topics individually, this book unifies the fields of autonomy and AI, framing them in the broader context of effective integration for human-autonomous machine and robotic systems. The contributions, written by world-class researchers and scientists, elaborate on key research topics at the heart of effective human-machine-robot-systems integration. These topics include, for example, computational support for intelligence analyses; the challenge of verifying today’s and future autonomous systems; comparisons between today’s machines and autism; implications of human information interaction on artificial intelligence and errors; systems that reason; the autonomy of machines, robots, buildings; and hybrid teams, where hybrid reflects arbitrary combinations of humans, machines and robots. The contributors span the field of autonomous systems research, ranging from industry and academia to government. Given the broad diversity of the research in this book, the editors strove to thoroughly examine the challenges and trends of systems that implement and exhibit AI; the social implications of present and future systems made autonomous with AI; systems with AI seeking to develop trusted relationships among humans, machines, and robots; and the effective human systems integration that must result for trust in these new systems and their applications to increase and to be sustained.

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