

Hrp 2 Humanoid Robot Papercraft

JA Banks

Build Your Own Paper Robots Julius Perdana, Josh Buczynski, Kurt Young, 2009-08-18 Presents projects, instructions, and color templates for fourteen paper robots.

Human-robot Interaction Sara Kiesler, Pamela Hinds, 2004-06-17 This special issue is made up of five articles which cover the emerging area of human-robot interaction. The first paper offers a theoretical ecological framework for the design of personal service robots in homes of elderly people. Next, a field study of two robots that visited a children's elementary school in Japan for two weeks, with the purpos

New Frontiers in Human-Robot Interaction Kerstin Dautenhahn, Joe Saunders, 2011-12-21 Human-Robot Interaction (HRI) considers how people can interact with robots in order to enable robots to best interact with people. HRI presents many challenges with solutions requiring a unique combination of skills from many fields, including computer science, artificial intelligence, social sciences, ethology and engineering. We have specifically aimed this work to appeal to such a multi-disciplinary audience. This volume presents new and exciting material from HRI researchers who discuss research at the frontiers of HRI. The chapters address the human aspects of interaction, such as how a robot may understand, provide feedback and act as a social being in interaction with a human, to experimental studies and field implementations of human-robot collaboration ranging from joint action, robots practically and safely helping people in real world situations, robots helping people via rehabilitation and robots acquiring concepts from communication. This volume reflects current trends in this exciting research field.

Introduction to Humanoid Robotics Shuuji Kajita, Hirohisa Hirukawa, Kensuke Harada, Kazuhito Yokoi, 2014-07-15 This book is for researchers, engineers, and students who are willing to understand how humanoid robots move and be controlled. The book starts with an overview of the humanoid robotics research history and state of the art. Then it explains the required mathematics and physics such as kinematics of multi-body system, Zero-Moment Point (ZMP) and its relationship with body motion. Biped walking control is discussed in depth, since it is one of the main interests of humanoid robotics. Various topics of the whole body motion generation are also discussed. Finally multi-body dynamics is presented to simulate the complete dynamic behavior of a humanoid robot. Throughout the book, Matlab codes are shown to test the algorithms and to help the reader's understanding.

Humanoid Robots Ben Choi, 2009-01-01 Humanoid robots are developed to use the infrastructures designed for humans, to ease the interactions with humans, and to help the integrations into human societies. The developments of humanoid robots proceed from building individual robots to establishing societies of robots working alongside with humans. This book addresses the problems of constructing a humanoid body and mind from generating walk patterns and balance maintenance to encoding and specifying humanoid motions and the control of eye and head movements for focusing attention on moving objects. It provides methods for learning motor skills and for language acquisition and describes how to generate facial movements for expressing various emotions and provides methods for decision making and planning. This book discusses the leading researches and challenges in building humanoid robots in order to prepare for the near future when human societies will be advanced by using humanoid robots.

3D Paper Craft Robots Patrick Pasques, 2012-08-28 A wonderfully entertaining and instructive compilation of 3D paper crafts.

The DARPA Robotics Challenge Finals: Humanoid Robots To The Rescue Matthew Spenko, Stephen Buerger, Karl Iagnemma, 2018-04-09 The DARPA Robotics Challenge was a robotics competition that took place in Pomona, California USA in June 2015. The competition was the culmination of 33 months of demanding work by 23 teams and required humanoid robots to perform challenging locomotion and manipulation tasks in a mock disaster site. The challenge was conceived as a response to the Japanese Fukushima nuclear disaster of March 2011. The Fukushima disaster was seen as an ideal candidate for robotic intervention since the risk of exposure to radiation prevented human responders from accessing the site. This volume, edited by Matthew Spenko, Stephen Buerger, and Karl Iagnemma, includes commentary by the organizers, overall analysis of the results, and documentation of the technical efforts of 15 competing teams. The book provides an important record of the successes and failures involved in the DARPA Robotics Challenge and provides guidance for future needs to be addressed by policy makers, funding agencies, and the robotics research community. Many of the papers in this volume were initially published in a series of special issues of the Journal of Field Robotics. We have proudly collected versions of those papers in this STAR volume.

Humanoid Robotics and Neuroscience Gordon Cheng, 2014-12-19 Humanoid robots are highly sophisticated machines equipped with human-like sensory and motor capabilities. Today we are on the verge of a new era of rapid transformations in both science and engineering—one that brings together technological advancements in a way that will accelerate both neuroscience and robotics. *Humanoid Robotics and Neuroscience: Science, Engineering and Society* presents the contributions of prominent scientists who explore key aspects of the further potential of these systems. Topics include: Neuroscientific research findings on dexterous robotic hand control Humanoid vision and how understanding the structure of the human eye can lead to improvements in artificial vision Humanoid locomotion, motor control, and the learning of motor skills Cognitive elements of humanoid robots, including the neuroscientific aspects of imitation and development The impact of robots on society and the potential for developing new systems and devices to benefit humans The use of humanoid robotics can help us develop a greater scientific understanding of humans, leading to the design of better engineered systems and machines for society. This book assembles the work of scientists on the cutting edge of robotic research who demonstrate the vast possibilities in this field of research.

Collaborative and Humanoid Robots Jesus Hamilton Ortiz, Ramana Vinjamuri, 2021-09-29 Collaborative and Humanoid Robots guides readers through the fundamentals and state-of-the-art concepts and future expectations of robotics. It showcases interesting research topics on robots and cobots by researchers, industry practitioners, and academics. Divided into two sections on “Collaborative Robots” and “Humanoid Robots,” this book includes surveys of recent publications that investigative the interaction between humanoid robots and humans; safe adaptive trajectory tracking control of robots; 3D printed, self-learning robots; robot trajectory, guidance, and control; social robots; Tiny Blind assistive humanoid robots; and more.

Origami Fun: Robots Elizabeth Neuenfeldt, 2020-08-01 Building a robot requires wires, metal, and knowledge of computers. But building an origami robot just takes a sheet or two of paper! With this hands-on origami guide, readers can construct favorite fictional robots, from Wall-E and Eva to BB-8 and the Iron Giant. Engaging text offers facts about each robot, while tips and tricks sidebars help with paper folding techniques.

Motion Planning for Humanoid Robots Kensuke Harada, Eiichi Yoshida, Kazuhito Yokoi, 2014-12-04 Research on humanoid robots has been mostly with the aim of developing robots that can replace humans in the performance of certain tasks. Motion planning for these robots can be quite difficult, due to their complex kinematics, dynamics and environment. It is consequently one of the key research topics in humanoid robotics research and the last few years have witnessed considerable progress in the field. *Motion Planning for Humanoid Robots* surveys the remarkable recent advancement in both the theoretical and the practical aspects of humanoid motion planning. Various motion planning frameworks are presented in *Motion Planning for Humanoid Robots*, including one for skill coordination and learning, and one for manipulating and grasping tasks. The problem of planning sequences of contacts that support acyclic motion in a highly constrained environment is addressed and a motion planner that enables a humanoid robot to push an object to a desired location on a cluttered table is described. The main areas of interest include: • whole body motion

planning, • task planning, • biped gait planning, and • sensor feedback for motion planning. Torque-level control of multi-contact behavior, autonomous manipulation of moving obstacles, and movement control and planning architecture are also covered. Motion Planning for Humanoid Robots will help readers to understand the current research on humanoid motion planning. It is written for industrial engineers, advanced undergraduate and postgraduate students.

Build Your Own Humanoid Robots Karl Williams,2004-03-23

Paper Robots Nick Knite,2013-09-15 In this book you will find 25 robots to assemble, each with a wild and unusual design and background story.

Disaster Robotics Satoshi Tadokoro,2019-01-20 This book introduces readers to the latest findings on disaster robotics. It is based on the ImPACT Tough Robotics Challenge, a national project spearheaded by the Japan Cabinet Office that focuses on developing robotics technologies to aid in disaster response, recovery and preparedness. It presents six subprojects that involve robot platforms and several component technologies used in conjunction with robots: cyber rescue canines, which are digitally empowered rescue dogs; serpent-like robots for searching debris; serpent-like robots for plant/infrastructure inspection; UAVs for gathering information on large areas struck by disaster; legged robots for plant/infrastructure inspection in risky places; and construction robots for recovery tasks that require both power and precision. The book offers a valuable source of information for researchers, engineers and practitioners in safety, security and rescue robotics, disaster robotics, and plant and infrastructure maintenance. It will also appeal to a wider demographic, including students and academics, as it highlights application scenarios and the total concept for each robot in various scientific and technical contexts. In addition to a wealth of figures and photos that explain these robots and systems, as well as experimental data, the book includes a comprehensive list of published papers from this project for readers to refer to. Lastly, an external website offers video footage and updated information from the International Rescue System Institute.

Advances in Robot Kinematics Jadran Lenarčič,Federico Thomas,2002-06-30 This book presents the most recent research advances in the theory, design, control, and application of robotic systems, which are intended for a variety of purposes such as manipulation, manufacturing, automation, surgery, locomotion, and biomechanics.

From Cave Man to Cave Martian Manfred "Dutch" von Ehrenfried,2019-04-05 This book explores the practicality of using the existing subsurface geology on the Moon and Mars for protection against radiation, thermal extremes, micrometeorites and dust storms rather than building surface habitats at great expense at least for those first few missions. It encourages NASA to plan a precursor mission using this concept and employ a “Short Stay” Opposition Class mission to Mars as the first mission rather than the “Long Stay” concept requiring a mission that is too long, too dangerous and too costly for man’s first missions to Mars. Included in these pages is a short history on the uses of caves by early humans over great periods of time. It then describes the ongoing efforts to research caves, pits, tunnels, lava tubes, skylights and the associated technologies that pertain to potential lunar and Mars exploration and habitation. It describes evidence for existing caves and lava tubes on both the Moon and Mars. The work of noted scientists, technologists and roboticists are referenced and described. This ongoing work is more extensive than one would think and is directly applicable to longer term habitation and exploration of the Moon and Mars. Emphasis is also given to the operational aspects of working and living in lunar and Martian caves and lava tubes.

Paper Based Sensors ,2020-06-13 Paper Based Sensors, Volume 89, the latest release in this comprehensive series that gathers the most important issues relating to the design and application of these cost-effective devices used in many industries, including health and environment diagnostics, safety and security, chemistry, optics, electrochemistry, nanoscience and nanotechnologies, presents the latest updates in the field. Chapters in this new release include Exploring paper as a substrate for electrochemical micro-devices, Paper-based sensors for application in biological compound detection, Printed paper-based (bio)sensors: design, fabrication and applications, Paper-based electrochemical sensing devices, Multifarious aspects of electrochemical paper-based (bio)sensors, Paper Based Biosensors for Clinical and Biomedical Applications, and more. Provides updates on the latest design in paper-based sensors using various nano and micromaterials Includes optical/electrical-based detection modes integrated within paper-based platforms Covers applications of paper-based platforms in diagnostics and other industries

Retail Visioning Christine Moynihan,2011-06-15 Easy to use work book designed for independent retailers. Full of self assessment tools and recommendations for improving retail branding,interior and exterior store design and retail marketing.

Designing with Photovoltaics Angèle Reinders,2020-04-30 Designing with Photovoltaics cover a broad range of topics related to the design of products, buildings and vehicles with integrated photovoltaic (PV) technologies including storage aspect. It enables the reader to easily design new products, buildings and vehicles through use of innovative PV products. Diverse categories of product integrated PVs are discussed including applications of solar power for mobility and building integrated systems along with design- and manufacturing-related information about solar cells. Illustrating design cases of various PV-powered products, special attention is paid to end-users and environmental aspects of PV applications. Aimed at senior undergraduates, graduates and professionals in electrical engineering, architecture, design, physics, mechanical engineering and those specifically studying photovoltaics, it Covers the different product integrated photovoltaics (PIPV) with a focus on design and manufacturing Presents comprehensive overview of all aspects of designing with photovoltaics Includes product integrated PV, building integrated PV and solar powered mobility concepts Contains real design cases showing how to design with photovoltaics Discusses context of environmental issues and user aspects

Advances in Robot Kinematics 2016 Jadran Lenarčič,Jean-Pierre Merlet,2018-08-07 This book brings together 46 peer-reviewed papers that are of interest to researchers wanting to know more about the latest topics and methods in the fields of the kinematics, control and design of robotic systems. These papers cover the full range of robotic systems, including serial, parallel and cable-driven manipulators, both planar and spatial. The systems range from being less than fully mobile, to kinematically redundant, to over-constrained. In addition to these more familiar areas, the book also highlights recent advances in some emerging areas: such as the design and control of humanoids and humanoid subsystems; the analysis, modeling and simulation of human-body motions; mobility analyses of protein molecules; and the development of machines that incorporate man.

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