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Joachim von Braun, Margaret S. Archer, Gregory M. Reichberg, Marcelo Sánchez Sorondo

Interfaces for Ground and Air Military Robots National Research Council, Division of Behavioral and Social Sciences and Education, Board on Behavioral, Cognitive, and Sensory Sciences, Committee on Human Factors, Planning Committee for the Workshop on Scalable Interfaces for Air and Ground Military Robots, 2005-03-21 In the early years of robotics and automated vehicles, the fight was against nature and not against a manifestly intelligent opponent. In military environments, however, where prediction and anticipation are complicated by the existence of an intelligent adversary, it is essential to retain human operators in the control loop. Future combat systems will require operators to control and monitor aerial and ground robotic systems and to act as part of larger teams coordinating diverse robotic systems over multiple echelons. The National Research Council organized a workshop to identify the most important human-related research and design issues from both the engineering and human factors perspectives, and develop a list of fruitful research directions. Interfaces for Ground and Air Military Robots summarizes the presentations and discussions from this workshop.

The Wild Robot Peter Brown, 2024-09-03 Soon to be a DreamWorks movie, coming to theaters 9/20/24! Wall-E meets Hatchet in this #1 New York Times bestselling illustrated middle grade novel from Caldecott Honor winner Peter Brown Can a robot survive in the wilderness? When robot Roz opens her eyes for the first time, she discovers that she is all alone on a remote, wild island. She has no idea how she got there or what her purpose is--but she knows she needs to survive. After battling a violent storm and escaping a vicious bear attack, she realizes that her only hope for survival is to adapt to her surroundings and learn from the island's unwelcoming animal inhabitants. As Roz slowly befriends the animals, the island starts to feel like home--until, one day, the robot's mysterious past comes back to haunt her. From bestselling and award-winning author and illustrator Peter Brown comes a heartwarming and action-packed novel about what happens when nature and technology collide.

Robotics, AI, and Humanity Joachim von Braun, Margaret S. Archer, Gregory M. Reichberg, Marcelo Sánchez Sorondo, 2022-01-16 This open access book examines recent advances in how artificial intelligence (AI) and robotics have elicited widespread debate over their benefits and drawbacks for humanity. The emergent technologies have for instance implications within medicine and health care, employment, transport, manufacturing, agriculture, and armed conflict. While there has been considerable attention devoted to robotics/AI applications in each of these domains, a fuller picture of their connections and the possible consequences for our shared humanity seems needed. This volume covers multidisciplinary research, examines current research frontiers in AI/robotics and likely impacts on societal well-being, human – robot relationships, as well as the opportunities and risks for sustainable development and peace. The attendant ethical and religious dimensions of these technologies are addressed and implications for regulatory policies on the use and future development of AI/robotics technologies are elaborated.

Duct Tape Engineer Lance Akiyama, 2017-02 Grab a roll of duct tape and get started on some unforgettable mega projects with Duct Tape Engineer: The Book of Big, Bigger, and Epic Duct Tape Projects.

Disaster Robotics Satoshi Tadokoro, 2019-01-20 This book introduces readers to the latest findings on disaster robotics. It is based on the ImPACT Tough Robotics Challenge, a national project spearheaded by the Japan Cabinet Office that focuses on developing robotics technologies to aid in disaster response, recovery and preparedness. It presents six subprojects that involve robot platforms and several component technologies used in conjunction with robots: cyber rescue canines, which are digitally empowered rescue dogs; serpent-like robots for searching debris; serpent-like robots for plant/infrastructure inspection; UAVs for gathering information on large areas struck by disaster; legged robots for plant/infrastructure inspection in risky places; and construction robots for recovery tasks that require both power and precision. The book offers a valuable source of information for researchers, engineers and practitioners in safety, security and rescue robotics, disaster robotics, and plant and infrastructure maintenance. It will also appeal to a wider demographic, including students and academics, as it highlights application scenarios and the total concept for each robot in various scientific and technical contexts. In addition to a wealth of figures and photos that explain these robots and systems, as well as experimental data, the book includes a comprehensive list of published papers from this project for readers to refer to. Lastly, an external website offers video footage and updated information from the International Rescue System Institute.

The Fourth Industrial Revolution Klaus Schwab, 2017-01-03 World-renowned economist Klaus Schwab, Founder and Executive Chairman of the World Economic Forum, explains that we have an opportunity to shape the fourth industrial revolution, which will fundamentally alter how we live and work. Schwab argues that this revolution is different in scale, scope and complexity from any that have come before. Characterized by a range of new technologies that are fusing the physical, digital and biological worlds, the developments are affecting all disciplines, economies, industries and governments, and even challenging ideas about what it means to be human. Artificial intelligence is already all around us, from supercomputers, drones and virtual assistants to 3D printing, DNA sequencing, smart thermostats, wearable sensors and microchips smaller than a grain of sand. But this is just the beginning: nanomaterials 200 times stronger than steel and a million times thinner than a strand of hair and the first transplant of a 3D printed liver are already in development. Imagine “smart factories” in which global systems of manufacturing are coordinated virtually, or implantable mobile phones made of biosynthetic materials. The fourth industrial revolution, says Schwab, is more significant, and its ramifications more profound, than in any prior period of human history. He outlines the key technologies driving this revolution and discusses the major impacts expected on government, business, civil society and individuals. Schwab also offers bold ideas on how to harness these changes and shape a better future—one in which technology empowers people rather than replaces them; progress serves society rather than disrupts it; and in which innovators respect moral and ethical boundaries rather than cross them. We all have the opportunity to contribute to developing new frameworks that advance progress.

Deep Maneuver Jack D Kern Editor, Jack Kern, 2018-10-12 Volume 5, Deep Maneuver: Historical Case Studies of

Maneuver in Large-Scale Combat Operations, presents eleven case studies from World War II through Operation Iraqi Freedom focusing on deep maneuver in terms of time, space and purpose. Deep operations require boldness and audacity, and yet carry an element of risk of overextension - especially in light of the independent factors of geography and weather that are ever-present. As a result, the case studies address not only successes, but also failure and shortfalls that result when conducting deep operations. The final two chapters address these considerations for future Deep Maneuver.

Fight Write Carla Hoch, 2019-06-11 Whether a side-street skirmish or an all-out war, fight scenes bring action to the pages of every kind of fiction. But a poorly done or unbelievable fight scene can ruin a great book in an instant. In Fight Write you'll learn practical tips, terminology, and the science behind crafting realistic fight scenes for your fiction. Broken up into Rounds, trained fighter and writer Carla Hoch guides you through the many factors you'll need to consider when developing battles and brawls. • In Round 1, you will consider how the Who, When, Where, and Why questions affect what type of fight scene you want to craft. • Round 2 delves into the human factors of biology (think fight or flight and adrenaline) and psychology (aggression and response to injuring or killing another person). • Round 3 explores different fighting styles that are appropriate for different situations: How would a character fight from a prone position versus being attacked in the street? What is the vocabulary used to describe these styles? • Round 4 considers weaponry and will guide you to select the best weapon for your characters, including nontraditional weapons of opportunity, while also thinking about the nitty-gritty details of using them. • In Round 5, you'll learn how to accurately describe realistic injuries sustained from the fights and certain weapons, and what kind of injuries will kill a character or render them unable to fight further. By taking into account where your character is in the world, when in history the fight is happening, what the character's motivation for fighting is, and much more, you'll be able write fight scenes unique to your plot and characters, all while satisfying your reader's discerning eye.

Virtual Reality National Research Council, Computer Science and Telecommunications Board, Committee on Virtual Reality Research and Development, 1995-01-13 Despite widespread interest in virtual reality, research and development efforts in synthetic environments (SE)â€the field encompassing virtual environments, teleoperation, and hybridsâ€have remained fragmented. Virtual Reality is the first integrated treatment of the topic, presenting current knowledge along with thought-provoking vignettes about a future where SE is commonplace. This volume discusses all aspects of creating a system that will allow human operators to see, hear, smell, taste, move about, give commands, respond to conditions, and manipulate objects effectively in a real or virtual environment. The committee of computer scientists, engineers, and psychologists on the leading edge of SE development explores the potential applications of SE in the areas of manufacturing, medicine, education, training, scientific visualization, and teleoperation in hazardous environments. The committee also offers recommendations for development of improved SE technology, needed studies of human behavior and evaluation of SE systems, and government policy and infrastructure.

Futureproof Kevin Roose,2021-03-09 A practical, deeply reported survival guide for the age of AI, written by the New York Times tech columnist who has introduced millions to the promise and pitfalls of artificial intelligence. “Artificial intelligence can be terrifying, but Kevin Roose provides a clear, compelling strategy for surviving the next wave of technology with our jobs—and souls—intact.”—Charles Duhigg, author of *The Power of Habit* It’s time to get real about AI. After decades of hype and sci-fi fantasies, AI—artificial intelligence—is leaping out of research labs and into the center of our lives. Millions of people now use tools like ChatGPT and DALL-E 2 to write essays, create art and finish coding projects. AI programs are already beating humans in fields like law, medicine and entertainment, and they’re getting better every day. But AI doesn’t just threaten our jobs. It shapes our entire human experience, steering our behavior and influencing our choices about which TV shows to watch, which clothes to buy, and which politicians to vote for. And while many experts argue about whether a robot apocalypse is near, one critical question has gone unanswered: In a world where AI is ascendant, how can humans survive and thrive? In *Futureproof: 9 Rules for Humans in the Age of Automation*, New York Times technology columnist Kevin Roose shares the secrets of people and organizations that have successfully navigated waves of technological change, and explains what skills are necessary to stay ahead of the curve today, with lessons like • Be surprising, social, and scarce • Resist machine drift • Leave handprints • Demote your devices • Treat AI like a chimp army Roose rejects the conventional wisdom that in order to compete with AI, we have to become more like robots ourselves—hyper-efficient, data-driven workhorses. Instead, he says, we should focus on being more human, and doing the kinds of creative, inspiring, and meaningful things even the most advanced algorithms can’t do.

Programming Robots with ROS Morgan Quigley,Brian Gerkey,William D. Smart,2015-11-16 Chapter 3. Topics; Publishing to a Topic; Checking That Everything Works as Expected; Subscribing to a Topic; Checking That Everything Works as Expected; Latched Topics; Defining Your Own Message Types; Defining a New Message; Using Your New Message; When Should You Make a New Message Type?; Mixing Publishers and Subscribers; Summary; Chapter 4. Services; Defining a Service; Implementing a Service; Checking That Everything Works as Expected; Other Ways of Returning Values from a Service; Using a Service; Checking That Everything Works as Expected; Other Ways to Call Services; Summary.

Aerial Manipulation Matko Orsag,Christopher Korpela,Paul Oh,Stjepan Bogdan,2017-09-19 This text is a thorough treatment of the rapidly growing area of aerial manipulation. It details all the design steps required for the modeling and control of unmanned aerial vehicles (UAV) equipped with robotic manipulators. Starting with the physical basics of rigid-body kinematics, the book gives an in-depth presentation of local and global coordinates, together with the representation of orientation and motion in fixed- and moving-coordinate systems. Coverage of the kinematics and dynamics of unmanned aerial vehicles is developed in a succession of popular UAV configurations for multirotor systems. Such an arrangement, supported by frequent examples and end-of-chapter exercises, leads the reader from simple to more complex UAV configurations. Propulsion-system aerodynamics, essential in UAV design, is analyzed through blade-element and momentum theories, analysis which is followed by a description of

drag and ground-aerodynamic effects. The central part of the book is dedicated to aerial-manipulator kinematics, dynamics, and control. Based on foundations laid in the opening chapters, this portion of the book is a structured presentation of Newton–Euler dynamic modeling that results in forward and backward equations in both fixed- and moving-coordinate systems. The Lagrange–Euler approach is applied to expand the model further, providing formalisms to model the variable moment of inertia later used to analyze the dynamics of aerial manipulators in contact with the environment. Using knowledge from sensor data, insights are presented into the ways in which linear, robust, and adaptive control techniques can be applied in aerial manipulation so as to tackle the real-world problems faced by scholars and engineers in the design and implementation of aerial robotics systems. The book is completed by path and trajectory planning with vision-based examples for tracking and manipulation.

Papertoy Monsters Brian Castleforte, 2010-12-29 A breakthrough paper-folding book for kids—paper airplanes meet Origami meets Pokemon. Papertoys, the Internet phenomenon that’s hot among graphic designers and illustrators around the world, now comes to kids in the coolest new book. Created and curated by Brian Castleforte, a graphic designer and papertoy pioneer who rounded up 25 of the hottest papertoy designers from around the world (Indonesia, Japan, Australia, Italy, Croatia, Chile, even Jackson, Tennessee), Papertoy Monsters offers 50 fiendishly original die-cut designs that are ready to pop out, fold, and glue. The book interleaves card stock with paper stock for a unique craft package; the graphics are colorful and hip, combining the edginess of anime with the goofy fun of Uglydolls and other collectibles. Plus each character comes with its own back-story. And the results are delicious: meet Pharaoh Thoth Amon, who once ruled Egypt but is now a mummy who practices dark magic in his sarcophagus. Or Zumbie the Zombie, who loves nothing more than a nice plate of brains and yams. NotSoScary, a little monster so useless at frightening people that he has to wear a scary mask. Yucky Chuck, the lunchbox creature born in the deepest depths of your school bag. Plus Zeke, the monster under your bed, Nom Nom, eater of cities, and Grumpy Gramps, the hairy grandpa monster with his very own moustache collection.

Robotics in Education Munir Merdan, Wilfried Lepuschitz, Gottfried Koppensteiner, Richard Balogh, David Obdržálek, 2019-08-06 This proceedings book gathers the latest achievements and trends in research and development in educational robotics from the 10th International Conference on Robotics in Education (RiE), held in Vienna, Austria, on April 10–12, 2019. It offers valuable methodologies and tools for robotics in education that encourage learning in the fields of science, technology, engineering, arts and mathematics (STEAM) through the design, creation and programming of tangible artifacts for creating personally meaningful objects and addressing real-world societal needs. It also discusses the introduction of technologies ranging from robotics platforms to programming environments and languages and presents extensive evaluations that highlight the impact of robotics on students’ interests and competence development. The approaches included cover the entire educative range, from the elementary school to the university level in both formal and informal settings.

Search and Rescue Robotics Multiple Authors, 2017-08-23 In the event of large crises (earthquakes, typhoons, floods, ...), a primordial task of the fire and rescue services is the search for human survivors on the incident

site. This is a complex and dangerous task, which - too often - leads to loss of lives among the human crisis managers themselves. This book explains how unmanned search can be added to the toolkit of the search and rescue workers, offering a valuable tool to save human lives and to speed up the search and rescue process. The introduction of robotic tools in the world of search and rescue is not straightforward, due to the fact that the search and rescue context is extremely technology-unfriendly, meaning that very robust solutions, which can be deployed extremely quickly, are required. Multiple research projects across the world are tackling this problem and in this book, a special focus is placed on showcasing the results of the European Union ICARUS project on this subject. The ICARUS project proposes to equip first responders with a comprehensive and integrated set of unmanned search and rescue tools, to increase the situational awareness of human crisis managers, so that more work can be done in a shorter amount of time. The ICARUS tools consist of assistive unmanned air, ground, and sea vehicles, equipped with victim-detection sensors. The unmanned vehicles collaborate as a coordinated team, communicating via ad hoc cognitive radio networking. To ensure optimal human-robot collaboration, these tools are seamlessly integrated into the command and control equipment of the human crisis managers and a set of training and support tools is provided to them in order to learn to use the ICARUS system. The research leading to these results has received funding from the European Community's Seventh Framework Programme (FP7/2007-2013) under grant agreement number 285417. The publishing of this book was funded by the EC FP7 Post-Grant Open Access Pilot programme.

Lethal and Non-Lethal Fires Army University Press, Thomas G. Bradbeer, 2018-09 *Lethal and Non-Lethal Fires: Historical Case Studies of Converging Cross-Domain Fires in Large Scale Combat Operations*, provides a collection of ten historical case studies from World War I through Desert Storm. The case studies detail the use of lethal and non-lethal fires conducted by US, British, Canadian, and Israeli forces against peer or near-peer threats. The case studies span the major wars of the twentieth-century and present the doctrine the various organizations used, together with the challenges the leaders encountered with the doctrine and the operational environment, as well as the leaders' actions and decisions during the conduct of operations. Most importantly, each chapter highlights the lessons learned from those large scale combat operations, how they were applied or ignored and how they remain relevant today and in the future.

AI for Game Developers David M Bourg, Glenn Seemann, 2004-07-23 Written for the novice AI programmer, this text introduces the reader to techniques such as finite state machines, fuzzy logic, neural networks and many others in an easy-to-understand language, supported with code samples throughout the text.

Free Software, Free Society Richard Stallman, 2002 Essay Collection covering the point where software, law and social justice meet.

The Longing for Less Kyle Chayka, 2020-01-21 The New Yorker staff writer and Filterworld author Kyle Chayka examines the deep roots-and untapped possibilities-of our newfound, all-consuming drive to reduce. "Less is more": Everywhere we hear the mantra. Marie Kondo and other decluttering gurus promise that shedding our stuff will solve our problems. We commit to cleanse diets and strive for inbox zero. Amid the frantic pace and distraction of

everyday life, we covet silence-and airy, Instagrammable spaces in which to enjoy it. The popular term for this brand of upscale austerity, “minimalism,” has mostly come to stand for things to buy and consume. But minimalism has richer, deeper, and altogether more valuable gifts to offer. In *The Longing for Less*, one of our sharpest cultural critics delves beneath the glossy surface of minimalist trends, seeking better ways to claim the time and space we crave. Kyle Chayka's search leads him to the philosophical and spiritual origins of minimalism, and to the stories of artists such as Agnes Martin and Donald Judd; composers such as John Cage and Julius Eastman; architects and designers; visionaries and misfits. As Chayka looks anew at their extraordinary lives and explores the places where they worked-from Manhattan lofts to the Texas high desert and the back alleys of Kyoto-he reminds us that what we most require is presence, not absence. The result is an elegant synthesis of our minimalist desires and our profound emotional needs. With a new afterword by the author.

How to Break Up with Your Phone Catherine Price, 2018-02-13 Packed with tested strategies and practical tips, this book is the essential, life-changing guide for everyone who owns a smartphone. Is your phone the first thing you reach for in the morning and the last thing you touch before bed? Do you frequently pick it up “just to check,” only to look up forty-five minutes later wondering where the time has gone? Do you say you want to spend less time on your phone—but have no idea how to do so without giving it up completely? If so, this book is your solution. Award-winning journalist Catherine Price presents a practical, hands-on plan to break up—and then make up—with your phone. The goal? A long-term relationship that actually feels good. You’ll discover how phones and apps are designed to be addictive, and learn how the time we spend on them damages our abilities to focus, think deeply, and form new memories. You’ll then make customized changes to your settings, apps, environment, and mindset that will ultimately enable you to take back control of your life.

Uncover the mysteries within is enigmatic creation, **Platform M Combat Robot Paper Model.jpg** . This downloadable ebook, shrouded in suspense, is available in a PDF format (PDF Size: *). Dive into a world of uncertainty and anticipation. Download now to unravel the secrets hidden within the pages.

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