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Modern Recording Techniques David Miles Huber, Robert E. Runstein, 2012-09-10 As the most popular and authoritative guide to recording Modern Recording Techniques provides everything you need to master the tools and day to day practice of music recording and production. From room acoustics and running a session to mic placement and designing a studio Modern Recording Techniques will give you a really good grounding in the theory and industry practice. Expanded to include the latest digital audio technology the 7th edition now includes sections on podcasting, new surround sound formats and HD and audio. If you are just starting out or looking for a step up in industry, Modern Recording Techniques provides an in depth excellent read- the must have book

Introduction to Embedded Systems, Second Edition Edward Ashford Lee, Sanjit Arunkumar Seshia, 2017-01-06 An introduction to the engineering principles of embedded systems, with a focus on modeling, design, and analysis of cyber-physical systems. The most visible use of computers and software is processing information for human consumption. The vast majority of computers in use, however, are much less visible. They run the engine, brakes, seatbelts, airbag, and audio system in your car. They digitally encode your voice and construct a radio signal to send it from your cell phone to a base station. They command robots on a factory floor, power generation in a power plant, processes in a chemical plant, and traffic lights in a city. These less visible computers are called embedded systems, and the software they run is called embedded software. The principal challenges in designing and analyzing embedded systems stem from their interaction with physical processes. This book takes a cyber-physical approach to embedded systems, introducing the engineering concepts underlying embedded systems as a technology and as a subject of study. The focus is on modeling, design, and analysis of cyber-physical systems, which integrate computation, networking, and physical processes. The second edition offers two new chapters, several new exercises, and other improvements. The book can be used as a textbook at the advanced undergraduate or introductory graduate level and as a professional reference for practicing engineers and computer scientists. Readers should have some familiarity with machine structures, computer programming, basic discrete mathematics and algorithms, and signals and systems.

Computer Networks Andrew S. Tanenbaum, Nickolas Feamster, 2019-02

Computer Networks Andrew S. Tanenbaum, David J. Wetherall, 2013-07-23 Appropriate for Computer Networking or Introduction to Networking courses at both the undergraduate and graduate level in Computer Science, Electrical Engineering, CIS, MIS, and Business Departments. Tanenbaum takes a structured approach to explaining how networks work from the inside out. He starts with an explanation of the physical layer of networking, computer hardware and transmission systems; then works his way up to network applications. Tanenbaum's in-depth application coverage includes email; the domain name system; the World Wide Web (both client-and server-side); and multimedia (including voice over IP, Internet radio video on demand, video conferencing, and streaming media.

Materials and Processes Barrie D. Dunn,2015-12-29 The objective of this book is to assist scientists and engineers select the ideal material or manufacturing process for particular applications; these could cover a wide range of fields, from light-weight structures to electronic hardware. The book will help in problem solving as it also presents more than 100 case studies and failure investigations from the space sector that can, by analogy, be applied to other industries. Difficult-to-find material data is included for reference. The sciences of metallic (primarily) and organic materials presented throughout the book demonstrate how they can be applied as an integral part of spacecraft product assurance schemes, which involve quality, material and processes evaluations, and the selection of mechanical and component parts. In this successor edition, which has been revised and updated, engineering problems associated with critical spacecraft hardware and the space environment are highlighted by over 500 illustrations including micrographs and fractographs. Space hardware captured by astronauts and returned to Earth from long durations in space are examined. Information detailed in the Handbook is applicable to general terrestrial applications including consumer electronics as well as high reliability systems associated with aeronautics, medical equipment and ground transportation. This Handbook is also directed to those involved in maximizing the relia bility of new materials and processes for space technology and space engineering. It will be invaluable to engineers concerned with the construction of advanced structures or mechanical and electronic sub-systems.

The Shock Absorber Handbook John C. Dixon,2008-02-28 Every one of the many millions of cars manufactured annually worldwide uses shock absorbers, otherwise known as dampers. These form a vital part of the suspension system of any vehicle, essential for optimizing road holding, performance and safety. This, the second edition of the Shock Absorber Handbook (first edition published in 1999), remains the only English language book devoted to the subject. Comprehensive coverage of design, testing, installation and use of the damper has led to the book's acceptance as the authoritative text on the automotive applications of shock absorbers. In this second edition, the author presents a thorough revision of his book to bring it completely up to date. There are numerous detail improvements, and extensive new material has been added particularly on the many varieties of valve design in the conventional hydraulic damper, and on modern developments such as electrorheological and magnetorheological dampers. The Shock Absorber Handbook, 2nd Edition provides a thorough treatment of the issues surrounding the design and selection of shock absorbers. It is an invaluable handbook for those working in industry, as well as a principal reference text for students of mechanical and automotive engineering.

Accuracy and Stability of Numerical Algorithms Nicholas J. Higham, 2002-01-01 Accuracy and Stability of Numerical Algorithms gives a thorough, up-to-date treatment of the behavior of numerical algorithms in finite precision arithmetic. It combines algorithmic derivations, perturbation theory, and rounding error analysis, all enlivened by historical perspective and informative quotations. This second edition expands and updates the coverage of the first edition (1996) and includes numerous improvements to the original material. Two new chapters treat symmetric indefinite systems and skew-symmetric systems, and nonlinear systems and Newton's method. Twelve new sections include coverage of additional error bounds for Gaussian elimination, rank revealing LU factorizations, weighted and constrained least squares problems, and the fused multiply-add operation found on some modern computer architectures.

<u>Ultrasonic Testing of Materials</u> Josef Krautkrämer,Herbert Krautkrämer,2013-03-14 The amendments of this third English edition with respect to the second one concern beside some printing errors the replacement of some pictures in part D by more modern ones and updating the list of stand ards to the state of the fourth German edition. J OSEF KRAUTKRÄMER Cologne, January 1983 Preface to the Second Edition This seeond English edition is based on the third German edition. In view of most recent teehnological advances it has beeome necessary in many instances to supplement the second German edition and to revise some parts completely. In addition to piezo-electric methods, others are now also extensively discussed in Chapter 8. As for the intensity method, ultrasonic holo graphy is treated in the new Section 9. 4. In Part B, for reasons of syste maties, the resonance method has been included under transit-time methods. It appeared necessary to elaborate in greater detail the definition of the properties of pulse-echo testing equipment and their measure ments (10. 4). The more recent findings of pulse spectroscopy (5. 6) and sound-emission analysis (12) are mentioned only in passing because their significance is still controversial. Apart from numerous additions, particularly those concerning automatic testing installations, Part C also contains a new chapter which deals with tests on nu cle ar reactors (28), as well as abrief discussion of surface-hardness tests (32. 4). It became impossible to include a critical analysis of the principal standards in Chapter 33.

The DARPA Robotics Challenge Finals: Humanoid Robots To The Rescue Matthew Spenko, Stephen Buerger, Karl lagnemma, 2018-04-09 The DARPA Robotics Challenge was a robotics competition that took place in Pomona, California USA in June 2015. The competition was the culmination of 33 months of demanding work by 23 teams and required humanoid robots to perform challenging locomotion and manipulation tasks in a mock disaster site. The challenge was conceived as a response to the Japanese

Fukushima nuclear disaster of March 2011. The Fukushima disaster was seen as an ideal candidate for robotic intervention since the risk of exposure to radiation prevented human responders from accessing the site. This volume, edited by Matthew Spenko, Stephen Buerger, and Karl lagnemma, includes commentary by the organizers, overall analysis of the results, and documentation of the technical efforts of 15 competing teams. The book provides an important record of the successes and failures involved in the DARPA Robotics Challenge and provides guidance for future needs to be addressed by policy makers, funding agencies, and the robotics research community. Many of the papers in this volume were initially published in a series of special issues of the Journal of Field Robotics. We have proudly collected versions of those papers in this STAR volume.

Introductory Grammar of Amharic Wolf Leslau, 2000 This book closes the gap for beginners who want to study the Amharic language and had difficulties in finding the right grammar for this purpose: The first grammar of Amharic, the national language of Ethiopia, was published by Hiob Ludolf in 1698. The Amharic grammar published by Praetorius in 1879 is based on Amharic religious texts and on scattered material, usually composed by missionaries. A milestone in the study of Amharic is Marcel Cohen's Traite de langue amharique (1936), but this grammar, too is not completely suited for beginners since the author's generalizations are at times aimed at linguists. The grammar that comes closest to the concept of a beginner's grammar is that of C.H. Dawkin (1960), yet this grammar is extremely short, does not give examples and does not introduce the student to the intricacies of the language. The new book gives all the grammatical forms and the sentences of the present grammar in Amharic script and in phonetic transcription. The illustrative examples have a free and a literal translation. This procedure should likewise prove to be useful for the Semitist as well as for the general linguist.

Practical Ship Design D.G.M. Watson,2002-02-22 The ever-growing demand for commercial activities at sea has meant that ships are rapidly developing and that the rules governing their construction and operation are changing. Practical Ship Design records these changes, their outcomes and the reasoning behind them. It deals with every aspect of ship design and handles a wide range of both merchant ships and naval ships with authority. It provides coverage of cargo ships and passenger ships, tugs, dredgers and other service craft. It also includes concept design, detail design, structural design, hydrodynamics design, the effect of regulations, the preparation of specifications and matters of costs and economics. Drawing on the author's extensive practical experience, Practical Ship Design is likely to interest everybody involved in the design, construction, repair and operation of ships. Students and the most experienced professionals will all benefit from the book's vast store of design data and its conclusions and recommendations.

Innovations in Electrical and Electronic Engineering Margarita N. Favorskaya, Saad Mekhilef, Rajendra Kumar Pandey, Nitin Singh, 2020-07-25 The book is a compilation of selected papers from 2020 International Conference on Electrical and Electronics Engineering (ICEEE 2020) held in National Power Training Institute HQ (Govt. of India) on February 21 – 22, 2020. The work focuses on the current development in the fields of electrical and electronics engineering like power generation, transmission and distribution, renewable energy sources and technology, power electronics and applications, robotics, artificial intelligence and IoT, control, and automation and instrumentation, electronics devices, circuits and systems, wireless and optical communication, RF and microwaves, VLSI, and signal processing. The book is beneficial for readers from both academia and industry.

Physics Concepts and Connections Henri M. Van Bemmel, John Myers, 2002

Robotic Tactile Sensing Ravinder S. Dahiya, Maurizio Valle, 2012-07-29 Future robots are expected to work closely and interact safely with real-world objects and humans alike. Sense of touch is important in this context, as it helps estimate properties such as shape, texture, hardness, material type and many more; provides action related information, such as slip detection; and helps carrying out actions such as rolling an object between fingers without dropping it. This book presents an in-depth description of the solutions available for gathering tactile data, obtaining aforementioned tactile information from the data and effectively using the same in various robotic tasks. The efforts during last four decades or so have yielded a wide spectrum of tactile sensing technologies and engineered solutions for both intrinsic and extrinsic touch sensors. Nowadays, new materials and structures are being explored for obtaining robotic skin with physical features like bendable, conformable, and stretchable. Such features are important for covering various body parts of robots or 3D surfaces. Nonetheless, there exist many more hardware, software and application related issues that must be considered to make tactile sensing an effective component of future robotic platforms. This book presents an in-depth analysis of various system related issues and presents the trade-offs one may face while developing an effective tactile sensing system. For this purpose, human touch sensing has also been explored. The design hints coming out of the investigations into human sense of touch can be useful in improving the effectiveness of tactile sensory modality in robotics and other machines. Better integration of tactile sensors on a robot's body is prerequisite for the effective utilization of tactile data. The concept of semiconductor devices based sensors is an interesting one, as it allows compact and fast tactile sensing systems with capabilities such as human-like spatio-temporal resolution. This book presents a comprehensive description of semiconductor devices based tactile sensing. In particular, novel Piezo Oxide Semiconductor Field Effect Transistor (POSFET) based approach for high resolution tactile sensing has been discussed in detail. Finally, the extension of semiconductors devices based sensors concept to large and flexile areas has been discussed for obtaining robotic or electronic skin. With its multidisciplinary scope, this book is suitable for graduate students and researchers coming from diverse areas such robotics (bio-robots, humanoids, rehabilitation etc.), applied materials, humans touch sensing, electronics, microsystems, and instrumentation. To better explain the concepts the text is supported by large number of figures.

Real Time Microcomputer Control of Industrial Processes S.G. Tzafestas, J.K. Pal, 2012-12-06 The introduction of the microprocessor in computer and system engineering has motivated the development of many new concepts and has simplified the design of many modern industrial systems. During the first decade of their life. microprocessors have shown a tremendous evolution in all possible directions (technology, power, functionality, I/O handling, etc). Of course putting the microprocessors and their environmental devices into properly operating systems is a complex and difficult task requiring high skills for melding and integrating hardware, and systemic components, software This book was motivated by the editors' feeling that a cohesive reference is needed providing a good coverage of modern industrial applications of microprocessor-based real time control, together with latest advanced methodological issues. Unavoidably a single volume cannot be exhaustive, but the present book contains a sufficient number of important real-time applications. The book is divided in two sections. Section I deals with general hardware, software and systemic topics, and involves six chapters. Chapter 1, by Gupta and Toong, presents an overview of the development of microprocessors during their first twelve years of existence. Chapter 2, by Dasgupta, deals with a number of system software concepts for real time microprocessor-based systems (task scheduling, memory management, input-output aspects, programming language requirements.

Pentagon 9/11 Alfred Goldberg,2007-09-05 The most comprehensive account to date of the 9/11 attack on the Pentagon and aftermath, this volume includes unprecedented details on the impact on the Pentagon building and personnel and the scope of the rescue, recovery, and caregiving effort. It features 32 pages of photographs and more than a dozen diagrams and illustrations not previously available.

3D Imaging, Analysis and Applications Yonghuai Liu, Nick Pears, Paul L. Rosin, Patrik Huber, 2020-09-11 This textbook is designed for postgraduate studies in the field of 3D Computer Vision. It also provides a useful reference for industrial practitioners; for example, in the areas of 3D data capture, computer-aided geometric modelling and industrial quality assurance. This second edition is a significant upgrade of existing topics with novel findings. Additionally, it has new material covering consumer-grade RGB-D cameras, 3D morphable models, deep learning on 3D datasets, as well as new applications in the 3D digitization of cultural heritage and the 3D phenotyping of

crops. Overall, the book covers three main areas: ● 3D imaging, including passive 3D imaging, active triangulation 3D imaging, active time-of-flight 3D imaging, consumer RGB-D cameras, and 3D data representation and visualisation; ● 3D shape analysis, including local descriptors, registration, matching, 3D morphable models, and deep learning on 3D datasets; and ● 3D applications, including 3D face recognition, cultural heritage and 3D phenotyping of plants. 3D computer vision is a rapidly advancing area in computer science. There are many real-world applications that demand high-performance 3D imaging and analysis and, as a result, many new techniques and commercial products have been developed. However, many challenges remain on how to analyse the captured data in a way that is sufficiently fast, robust and accurate for the application. Such challenges include metrology, semantic segmentation, classification and recognition. Thus, 3D imaging, analysis and their applications remain a highly-active research field that will continue to attract intensive attention from the research community with the ultimate goal of fully automating the 3D data capture, analysis and inference pipeline.

Tika in Action Jukka L. Zitting, Chris Mattmann, 2011-11-30 Summary Tika in Action is a hands-on guide to content mining with Apache Tika. The book's many examples and case studies offer real-world experience from domains ranging from search engines to digital asset management and scientific data processing. About the Technology Tika is an Apache toolkit that has built into it everything you and your app need to know about file formats. Using Tika, your applications can discover and extract content from digital documents in almost any format, including exotic ones. About this Book Tika in Action is the ultimate guide to content mining using Apache Tika. You'll learn how to pull usable information from otherwise inaccessible sources, including internet media and file archives. This example-rich book teaches you to build and extend applications based on real-world experience with search engines, digital asset management, and scientific data processing. In addition to architectural overviews, you'll find detailed chapters on features like metadata extraction, automatic language detection, and custom parser development. This book is written for developers who are new to both Scala and Lift and covers just enough Scala to get you started. Purchase of the print book comes with an offer of a free PDF, ePub, and Kindle eBook from Manning. Also available is all code from the book. What's Inside Crack MS Word, PDF, HTML, and ZIP Integrate with search engines, CMS, and other data sources Learn through experimentation Many examples This book requires no previous knowledge of Tika or text mining techniques. It assumes a working knowledge of Java.

Professional Microphone Techniques David Miles Huber, Philip Williams, 1998 This book, by the author of industry bestseller Modern Recording Techniques, focuses on microphone usage for dozens of different instruments as well as vocals, amplifiers, Leslie cabinets and much more! Accompanied by an audio CD that allows you to hear the different effects of microphone placement techniques in real time for a full understanding of how to get the best recordings from any type of microphone!

Computer Vision for Autonomous Vehicles Joel Janai, Fatma Güney, Aseem Behl, Andreas Geiger, 2020 Recent years have witnessed enormous progress in Al-related fields such as computer vision, machine learning, and autonomous vehicles. As with any rapidly growing field, it becomes increasingly difficult to stay up-to-date or enter the field as a beginner. While several survey papers on particular sub-problems have appeared, no comprehensive survey on problems, datasets, and methods in computer vision for autonomous vehicles has been published. This monograph attempts to narrow this gap by providing a survey on the state-of-the-art datasets and techniques. Our survey includes both the historically most relevant literature as well as the current state of the art on several specific topics, including recognition, reconstruction, motion estimation, tracking, scene understanding, and end-to-end learning for autonomous driving. Towards this goal, we analyze the performance of the state of the art on several challenging benchmarking datasets, including KITTI, MOT, and Cityscapes. Besides, we discuss open problems and current research challenges. To ease accessibility and accommodate missing references, we also provide a website that allows navigating topics as well as methods and provides additional information.

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