

Sliding

Christopher Edwards,Sarah K. Spurgeon

Sliding Mode Control Using Novel Sliding Surfaces B. Bandyopadhyay, Fulwani Deepak, Kyung-Soo Kim, 2009-09-23 After a survey paper by Utkin in the late 1970s, sliding mode control methodologies emerged as an effective tool to tackle uncertainty and disturbances which are inevitable in most of the practical systems. Sliding mode control is a particular class of variable structure control which was introduced by Emel'yanov and his colleagues. The design paradigms of sliding mode control has now become a mature design technique for the design of robust controller of uncertain system. In sliding mode technique, the state trajectory of the system is constrained on a chosen manifold (or within some neighborhood thereof) by an appropriate control action. This manifold is also called a switching surface or a sliding surface. During sliding mode, system dynamics is governed by the chosen manifold which results in a well celebrated invariance property towards certain classes of disturbance and model mismatches. The purpose of this monograph is to give a different dimension to sliding surface design to achieve high performance of the system. Design of the switching surface is vital because the closed loop dynamics is governed by the parameters of the sliding surface. Therefore sliding surface should be designed to meet the closed loop specifications. Many systems demand high performance with robustness. To address this issue of achieving high performance with robustness, we propose nonlinear surfaces for different classes of systems. The nonlinear surface is designed such that it changes the system's closed-loop damping ratio from its initial low value to a final high value.

Sliding Mode Control Andrzej Bartoszewicz, 2011-04-11 The main objective of this monograph is to present a broad range of well worked out, recent application studies as well as theoretical contributions in the field of sliding mode control system analysis and design. The contributions presented here include new theoretical developments as well as successful applications of variable structure controllers primarily in the field of power electronics, electric drives and motion steering systems. They enrich the current state of the art, and motivate and encourage new ideas and solutions in the sliding mode control area.

Sliding Jane Foster, 2015-08-19 2015 Eric Hoffer Award Finalist Sliding is a touching and funny novel set in New York and Chicago in the mid-1980's. Friends since childhood, two attractive single women in their early thirties grapple with life's problems and provide support for each other. Follow Daphne and Maggie through changing life season as they journey through marriage, children, divorce, wealth, alcoholism, truth and love. Whether you are already present for someone going through difficult times or simply want inspiration you'll be carried right along as Foster treats the events with wit and wisdom to produce an entertaining yet cautionary tale.

Sliding Patricia Whitehouse, 2004 Presents simple hands-on experiments that demonstrate the properties that make sliding easier or more difficult.

Sliding Ellen Labrecque, 2018-01-01 Using the new C3 Framework for Social Studies Standards, Sliding in the Global Citizens: Olympic Sports series explores the sport through the lenses of History, Geography, Civics, and Economics. Text and photos look at the history, basic philosophies, and geography of sliding. Content includes information on multiple Olympic events in the sliding category, including luge and bobsled. As they read, students will develop questions about the text, and use evidence from a variety of sources in order to form conclusions. Data-focused backmatter is included, as well as a bibliography, glossary, and index.

Sliding Home Kate Angell, 2009 The ultimate bad boy baseball player finds a stranger in his shower and decides that no matter how sexy the interloper is, she won't find a place in his life—little does he know that the baseball diamond is not the only place he'll be sliding home.

Sliding in the Snow Melissa Dymock, 2015-07-14 Grab your gloves and snow boots, it's time for an adventure in a frozen wonderland—right in your own backyard! Here are fun twists on classic winter pastimes, like sledding and making snowmen. Learn how to design your own backyard winter Olympics. Things to make and do include: • Saving a Snowflake Forever • Wacky Snow Creations • Making Your Own Snowshoes • Making a Snowball Launcher • Sidewalk Curling • Skijoring • And more! MELISSA DYMOCK is a ski instructor for children ages 3 to 12 and has mastered getting six 5-year-olds dressed and on skis before any of them have to go the bathroom again (most days). For more outdoor adventures, find her at weekendwomanwarrior.com. She lives in Utah. FRAN LEE has a MFA from the School of the Art Institute of Chicago in Printmaking and a freelance graphic designer and illustrator (www.coatimundistudios.com). She has designed and illustrated many children's activity books and has been the Art Director for Chicago Review Press and Creative Director for Hello Kitty (Sanrio Inc.). She lives in Portland, Oregon, with her husband.

Advances in Sliding Mode Control B Bandyopadhyay, S Janardhanan, Sarah K. Spurgeon, 2013-03-15 The sliding mode control paradigm has become a mature technique for the design of robust controllers for a wide class of systems including nonlinear, uncertain and time-delayed systems. This book is a collection of plenary and invited talks delivered at the 12th IEEE International Workshop on Variable Structure System held at the Indian Institute of Technology, Mumbai, India in January 2012. After the workshop, these researchers were invited to develop book chapters for this edited collection in order to reflect the latest results and open research questions in the area. The contributed chapters have been organized by the editors to reflect the various themes of sliding mode control which are the current areas of theoretical research and applications focus; namely articulation of the fundamental underpinning theory of the sliding mode design paradigm, sliding modes for decentralized system representations, control of time-delay systems, the higher order sliding mode concept, results applicable to nonlinear and underactuated systems, sliding mode observers, discrete sliding mode control together with cutting edge research contributions in the application of the sliding mode concept to real world problems. This book provides the reader with a clear and complete picture of the current trends in Variable Structure Systems and Sliding Mode Control Theory.

Skeleton Kim Covert, 2005 Introduces the sport of skeleton, including history, equipment, and famous skeleton athletes.

Sliding Mode Control in Electro-mechanical Systems Vadim Utkin, Juergen Guldner, Ma Shijun, 1999-04-22 Sliding Mode Control (SMC) is gaining increasing importance as a universal design tool for the robust control of linear and nonlinear systems. The strengths of sliding mode controllers result from the ease and flexibility of the methodology for their design and implementation. They provide inherent order reduction, direct incorporation of robustness against system uncertainties and disturbances, and an implicit stability proof. They also allow for the design of high performance control systems at low costs. SMC is particularly useful for electro-mechanical systems because of its discontinuous structure. In fact, since the hardware of many electro-mechanical systems (such as electric motors) prescribes discontinuous inputs, SMC has become the natural choice for direct implementation. The book is intended primarily for engineers and establishes an interdisciplinary bridge between control science, electrical and mechanical engineering.

Discrete-time Sliding Mode Control B. Bandyopadhyay, S. Janardhanan, 2005-10-17 Sliding mode control is a simple and yet robust control technique, where the system states are made to confine to a selected subset. With the increasing use of computers and discrete-time samplers in controller implementation in the recent past, discrete-time systems and computer based control have become important topics. This monograph presents an output feedback sliding mode control philosophy which can be applied to almost all controllable and observable systems, while at the same time being simple enough as not to tax the computer too much. It is shown that the solution can be found in the synergy of the multirate output sampling concept and the concept of discrete-time sliding mode control.

Sliding Mode Control In Engineering Wilfrid Perruquetti, Jean-Pierre Barbot, 2002-01-29 Provides comprehensive coverage of the most recent developments in the theory of non-Archimedean pseudo-differential equations and its application to stochastics and mathematical physics--offering current methods of construction for stochastic processes in the field of p-adic numbers and related structures. Develops a new theory for parabolic equations

Sliding Modes in Control and Optimization Vadim I. Utkin, 2013-03-12 The book is devoted to systems with discontinuous control. The study of discontinuous dynamic systems is a multifacet problem which embraces mathematical, control theoretic and application aspects. Times and again, this problem has been approached by mathematicians, physicists and engineers, each profession treating it from its own positions. Interestingly, the results obtained by specialists in different disciplines have almost always had a significant effect upon the development of the control theory. It suffices to mention works on the theory of oscillations of

discontinuous nonlinear systems, mathematical studies in ordinary differential equations with discontinuous righthand parts or variational problems in nonclassic statements. The unremitting interest to discontinuous control systems enhanced by their effective application to solution of problems most diverse in their physical nature and functional purpose is, in the author's opinion, a cogent argument in favour of the importance of this area of studies. It seems a useful effort to consider, from a control theoretic viewpoint, the mathematical and application aspects of the theory of discontinuous dynamic systems and determine their place within the scope of the present-day control theory. The first attempt was made by the author in 1975-1976 in his course on The Theory of Discontinuous Dynamic Systems and The Theory of Variable Structure Systems read to post-graduates at the University of Illinois, USA, and then presented in 1978-1979 at the seminars held in the Laboratory of Systems with Discontinuous Control at the Institute of Control Sciences in Moscow.

Who's Hatching? Charles Reasoner,1994 Readers slide open the pages to discover the surprise baby hiding inside each egg.

Modern Sliding Mode Control Theory Giorgio Bartolini,Leonid Fridman,Alessandro Pisano,Elio Usai,2008-04-24 This concise book covers modern sliding mode control theory. The authors identify key contributions defining the theoretical and applicative state-of-the-art of the sliding mode control theory and the most promising trends of the ongoing research activities.

Sliding Leslie Norris,1981

Sliding Mode Control Christopher Edwards,Sarah K. Spurgeon,1998-08-27 In the formation of any control problem there will be discrepancies between the actual plant and the mathematical model for controller design. Sliding mode control theory seeks to produce controllers to over some such mismatches. This text provides the reader with a grounding in sliding mode control and is appropriate for the graduate with a basic knowledge of classical control theory and some knowledge of state-space methods.

Sliding Base Structures Hong-Song Hu,2023-08-11 This open access book is an efficient and economic approach for mitigating the seismic damage of low-rise buildings. This book presents various aspects of SB structures, including their fundamentals, dynamic analysis procedures, seismic response characteristics, design methods, and practical applications. It contains a comprehensive study on the influence of various structural and ground motion characteristics on the responses of SB structures, which is particularly helpful for the readers to fully understand the behavior of SB structures. Researchers and engineers in the field of structural engineering and earthquake engineering will benefit from this book.

Sliding-Mode Fuzzy Controllers Mojtaba Ahmadi Khansar,Okay Kaynak,Erdal Kayacan,2021-07-21 This book addresses some of the challenges suffered by the well-known and robust sliding-mode control paradigm. The authors show how the fusion of fuzzy systems with sliding-mode controllers can alleviate some of these problems and promote applicability. Fuzzy systems used as soft switches eliminate high-frequency signal oscillations and can substantially lower the noise sensitivity of sliding-mode controllers. The amount of a priori knowledge required concerning the nominal structure and parameters of a nonlinear system is also shown to be much reduced by exploiting the general function-approximation property of fuzzy systems so as to use them as identifiers. The main features of this book include: • a review of various existing structures of sliding-mode fuzzy control; • a guide to the fundamental mathematics of sliding-mode fuzzy controllers and their stability analysis; • state-of-the-art procedures for the design of a sliding-mode fuzzy controller; • source codes including MATLAB® and Simulink® codes illustrating the simulation of these controllers, particularly the adaptive controllers; • a short bibliography for each chapter for readers interested in learning more on a particular subject; and • illustrative examples and simulation results to support the main claims made in the text. Academic researchers and graduate students interested in the control of nonlinear systems and particularly those working in sliding-mode controller design will find this book a valuable source of comparative information on existing controllers and ideas for the development of new ones.

Recent Advances in Sliding Modes: From Control to Intelligent Mechatronics Xinghuo Yu,Mehmet Önder Efe,2015-04-10 This volume is dedicated to Professor Okay Kaynak to commemorate his life time impactful research and scholarly achievements and outstanding services to profession. The 21 invited chapters have been written by leading researchers who, in the past, have had association with Professor Kaynak as either his students and associates or colleagues and collaborators. The focal theme of the volume is the Sliding Modes covering a broad scope of topics from theoretical investigations to their significant applications from Control to Intelligent Mechatronics.

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