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Yoseph Bar-Cohen, David Hanson

<u>Build Your Own Paper Robots</u> Julius Perdana, Josh Buczynski, Kurt Young, 2009-08-18 Presents projects, instructions, and color templates for fourteen paper robots.

Biologically Inspired Robotics Yunhui Liu, Dong Sun, 2011-12-21 Robotic engineering inspired by biology—biomimetics—has many potential applications: robot snakes can be used for rescue operations in disasters, snake-like endoscopes can be used in medical diagnosis, and artificial muscles can replace damaged muscles to recover the motor functions of human limbs. Conversely, the application of robotics technology to our understanding of biological systems and behaviors—biorobotic modeling and analysis—provides unique research opportunities: robotic manipulation technology with optical tweezers can be used to study the cell mechanics of human red blood cells, a surface electromyography sensing system can help us identify the relation between muscle forces and hand movements, and mathematical models of brain circuitry may help us understand how the cerebellum achieves movement control. Biologically Inspired Robotics contains cutting-edge material—considerably expanded and with additional analysis—from the 2009 IEEE International Conference on Robotics and Biomimetics (ROBIO). These 16 chapters cover both biomimetics and biorobotic modeling/analysis, taking readers through an exploration of biologically inspired robot design and control, micro/nano bio-robotic systems, biological measurement and actuation, and applications of robotics technology to biological problems. Contributors examine a wide range of topics, including: A method for controlling the motion of a robotic snake The design of a bionic fitness cycle inspired by the jaguar The use of autonomous robotic fish to detect pollution A noninvasive brain-activity scanning method using a hybrid sensor A rehabilitation system for recovering motor function in human hands after injury Human-like robotic eye and head movements in human-machine interactions A state-of-the-art resource for graduate students and researchers in the fields of control engineering, robotics, and biomedical engineering, this text helps readers understand the technology and principles in this emerging field.

Template Matching Techniques in Computer Vision Roberto Brunelli, 2009-04-29 The detection and recognition of objects in images is a key research topic in the computer vision community. Within this area, face recognition and interpretation has attracted increasing attention owing to the possibility of unveiling human perception mechanisms, and for the development of practical biometric systems. This book and the accompanying website, focus on template matching, a subset of object recognition techniques of wide applicability, which has proved to be particularly effective for face recognition applications. Using examples from face processing tasks throughout the book to illustrate more general object recognition approaches, Roberto Brunelli: examines the basics of digital image formation, highlighting points critical to the task of template matching; presents basic and advanced template matching techniques, targeting grey-level images, shapes and point sets; discusses recent pattern classification paradigms from a template matching perspective; illustrates the development of a real face recognition system; explores the use of advanced computer graphics techniques in the development of computer vision algorithms. Template Matching Techniques in Computer Vision is primarily aimed at practitioners working on the development of systems for effective object recognition such as biometrics, robot navigation, multimedia retrieval and landmark detection. It is also of interest to graduate students undertaking studies in these areas.

Robot Manipulation of Deformable Objects Dominik Henrich, Heinz Wörn, 2012-12-06 This book is about automatic handling of non-rigid or deformable objects like cables, fabric, or foam rubber. The automation by robots in industrial environments, is especially examined. It discusses several important automation aspects, such as material modelling and simulation, planning and control strategies, collaborative systems, and industrial applications. This book collects contributions from various countries and

international projects and, therefore, provides a representative overview of the state of the art in this field. It is of particular interest for scientists and practitioners in the area of robotics and automation

Robot Fish Ruxu Du,Zheng Li,Kamal Youcef-Toumi,Pablo Valdivia y Alvarado,2015-05-06 This book provides a comprehensive coverage on robot fish including design, modeling and optimization, control, autonomous control and applications. It gathers contributions by the leading researchers in the area. Readers will find the book very useful for designing and building robot fish, not only in theory but also in practice. Moreover, the book discusses various important issues for future research and development, including design methodology, control methodology, and autonomous control strategy. This book is intended for researchers and graduate students in the fields of robotics, ocean engineering and related areas.

The Future of Humanoid Robots Riadh Zaier,2012-01-20 This book provides state of the art scientific and engineering research findings and developments in the field of humanoid robotics and its applications. It is expected that humanoids will change the way we interact with machines, and will have the ability to blend perfectly into an environment already designed for humans. The book contains chapters that aim to discover the future abilities of humanoid robots by presenting a variety of integrated research in various scientific and engineering fields, such as locomotion, perception, adaptive behavior, human-robot interaction, neuroscience and machine learning. The book is designed to be accessible and practical, with an emphasis on useful information to those working in the fields of robotics, cognitive science, artificial intelligence, computational methods and other fields of science directly or indirectly related to the development and usage of future humanoid robots. The editor of the book has extensive R

Beginning Diango Daniel Rubio, 2017-10-27 Discover the Diango web application framework and get started building Python-based web applications. This book takes you from the basics of Django all the way through to cutting-edge topics such as creating RESTful applications. Beginning Django also covers ancillary, but essential, development topics, including configuration settings, static resource management, logging, debugging, and email. Along with material on data access with SQL queries, you'll have all you need to get up and running with Django 1.11 LTS, which is compatible with Python 2 and Python 3. Once you've built your web application, you'll need to be the admin, so the next part of the book covers how to enforce permission management with users and groups. This technique allows you to restrict access to URLs and content, giving you total control of your data. In addition, you'll work with and customize the Django admin site, which provides access to a Django project's data. After reading and using this book, you'll be able to build a Django application top to bottom and be ready to move on to more advanced or complex Django application development. What You'll Learn Get started with the Django framework Use Django views, class-based views, URLs, middleware, forms, templates, and Jinja templates Take advantage of Django models, including model relationships, migrations, queries, and forms Leverage the Django admin site to get access to the database used by a Django project Deploy Django REST services to serve as the data backbone for mobile, IoT, and SaaS systems Who This Book Is For Python developers new to the Django web application development framework and web developers new to Python and Django.

Web 2.0 Miltiadis D. Lytras, Ernesto Damiani, Patricia Ordóñez de Pablos, 2008-10-20 While the web itself is about twenty years old, businesses are still impleme- ing the technology into the fabric of the business model. The background section will focus on defining the building blocks for the framework including defining the basic components of Web 1. 0 which focused on the presence and business transaction. The Web 2. 0 section will focus on defining the basic building blocks of customer interactions, while the final section will focus on a review the wine industry. 2. 1 Web 1. 0: Presence and Electronic Commerce

The term Web 1. 0 emerged from the research around the development of Web 2. 0. Prior to this, researchers commonly referred to Web 1. 0 as Electronic C- merce or E-Business. Where as, web 1. 0 focused on a read only web interface, Web 2. 0 focuses on a read-write interface where value emerges from the contri- tion of a large volume of users. The Internet initially focused on the command and control of the information itself. Information was controlled by a relative small number of resources but distributed to a large number which spawned the massive growth of the web itself. Like television before it, the web allowed for the broadcasting of information to a large number of users. Initial web sites were built simply to communicate presence or provide information on the business - self. This component includes information like marketing materials, investor re- tions, employment opportunities, and product information.

Essentials of Metaheuristics (Second Edition) Sean Luke, 2012-12-20 Interested in the Genetic Algorithm? Simulated Annealing? Ant Colony Optimization? Essentials of Metaheuristics covers these and other metaheuristics algorithms, and is intended for undergraduate students, programmers, and non-experts. The book covers a wide range of algorithms, representations, selection and modification operators, and related topics, and includes 71 figures and 135 algorithms great and small. Algorithms include: Gradient Ascent techniques, Hill-Climbing variants, Simulated Annealing, Tabu Search variants, Iterated Local Search, Evolution Strategies, the Genetic Algorithm, the Steady-State Genetic Algorithm, Differential Evolution, Particle Swarm Optimization, Genetic Programming variants, One- and Two-Population Competitive Coevolution, N-Population Cooperative Coevolution, Implicit Fitness Sharing, Deterministic Crowding, NSGA-II, SPEA2, GRASP, Ant Colony Optimization variants, Guided Local Search, LEM, PBIL, UMDA, cGA, BOA, SAMUEL, ZCS, XCS, and XCSF.

The Everything Store Brad Stone,2013-10-15 The authoritative account of the rise of Amazon and its intensely driven founder, Jeff Bezos, praised by the Seattle Times as the definitive account of how a tech icon came to life. Amazon.com started off delivering books through the mail. But its visionary founder, Jeff Bezos, wasn't content with being a bookseller. He wanted Amazon to become the everything store, offering limitless selection and seductive convenience at disruptively low prices. To do so, he developed a corporate culture of relentless ambition and secrecy that's never been cracked. Until now. Brad Stone enjoyed unprecedented access to current and former Amazon employees and Bezos family members, giving readers the first in-depth, fly-on-the-wall account of life at Amazon. Compared to tech's other elite innovators -- Jobs, Gates, Zuckerberg -- Bezos is a private man. But he stands out for his restless pursuit of new markets, leading Amazon into risky new ventures like the Kindle and cloud computing, and transforming retail in the same way Henry Ford revolutionized manufacturing. The Everything Store is the revealing, definitive biography of the company that placed one of the first and largest bets on the Internet and forever changed the way we shop and read.

Free-to-Play Will Luton, 2013-05-27 "Will's knowledge of F2P comes from years of building games, as well as writing about and consulting with developers on the model. All the topics covered in this book—economics, gameplay, monetization, analytics and marketing—are important to consider when you're building an F2P game, and Will covers each with an easy-to-digest style." —Ian Marsh, co-founder, NimbleBit Free-to-Play: Making Money From Games You Give Away is an accessible and complete guide to the business model that has revolutionized the videogames industry, creating huge hits, multi-billion-dollar startups and a new deal for players: Play for free, spend on what you like. Written by respected game designer and consultant Will Luton, Free-to-Play gives you the in-the-trenches insight you need to build, run and make money from games you give away. In it you'll find: Psychology behind player decisions and the motivations to play Simple and accessible explanations of the math and economic theories behind F2P, including working

examples Processes for capturing and using player data to improve your game Marketing tips on positioning your game and attracting players Plus: A downloadable F2P spreadsheet, articles from the author, a foreword by NimbleBit co-founder Ian Marsh and an interview with Zynga CEO, Mark Pincus.

The Coming Robot Revolution Yoseph Bar-Cohen, David Hanson, 2009-04-20 Making a robot that looks and behaves like a human being has been the subject of many popular science fiction movies and books. Although the development of such a robot facesmanychallenges, themaking of a virtual human has long been potentially possible. With recent advances in various key technologies related to hardware and software, the making of humanlike robots is increasingly becoming an engineering reality. Development of the required hardware that can perform humanlike functions in a lifelike manner has benefitted greatly from development in such technologies as biologically inspired materials, artificial intelligence, artificial vision, and many others. Producing a humanlike robot that makes body and facial expressions, communicates verbally using extensive vocabulary, and interprets speech with high accuracy is ext- mely complicated to engineer. Advances in voice recognition and speech synthesis are increasingly improving communication capabilities. In our daily life we encounter such innovations when we call the telephone operators of most companies today. As robotics technology continues to improve we are approaching the point where, on seeing such a robot, we will respond with "Wow, this robot looks unbelievably real!" just like the reaction to an artificial flower. The accelerating pace of advances in related fields suggests that the emergence of humanlike robots that become part of our daily life seems to be imminent. These robots are expected to raise ethical concerns and may also raise many complex questions related to their interaction with humans.

ROBOT2013: First Iberian Robotics Conference Manuel A. Armada, Alberto Sanfeliu, Manuel Ferre, 2013-11-12 This book contains the proceedings of the ROBOT 2013: FIRST IBERIAN ROBOTICS CONFERENCE and it can be said that included both state of the art and more practical presentations dealing with implementation problems, support technologies and future applications. A growing interest in Assistive Robotics, Agricultural Robotics, Field Robotics, Grasping and Dexterous Manipulation, Humanoid Robots, Intelligent Systems and Robotics, Marine Robotics, has been demonstrated by the very relevant number of contributions. Moreover, ROBOT2013 incorporates a special session on Legal and Ethical Aspects in Robotics that is becoming a topic of key relevance. This Conference was held in Madrid (28-29 November 2013), organized by the Sociedad Española para la Investigación y Desarrollo en Robótica (SEIDROB) and by the Centre for Automation and Robotics - CAR (Universidad Politécnica de Madrid (UPM) and Consejo Superior de Investigaciones Científicas (CSIC)), along with the co-operation of Grupo Temático de Robótica CEA-GTRob, Sociedade Portuguesa de Robotica (SPR), Asociación Española de Promoción de la Investigación en Agentes Físicos (RedAF), and partially supported by Comunidad de Madrid under RoboCity2030 Programme.

Pattern Recognition and Image Analysis Jorge S. Marques, 2005-05-23 The two-volume set LNCS 3522 and 3523 constitutes the refereed proceedings of the Second Iberian Conference on Pattern Recognition and Image Analysis, IbPRIA 2005, held in Estoril, Portugal in June 2005. The 170 revised full papers presented were carefully reviewed and selected from 292 submissions. The papers are organized in topical sections on computer vision, shape and matching, image and video processing, image and video coding, face recognition, human activity analysis, surveillance, robotics, hardware architectures, statistical pattern recognition, syntactical pattern recognition, image analysis, document analysis, bioinformatics, medical imaging, biometrics, speech recognition, natural language analysis, and applications.

Freemium Economics Eric Benjamin Seufert, 2013-12-27 Freemium Economics

presents a practical, instructive approach to successfully implementing the freemium model into your software products by building analytics into product design from the earliest stages of development. Your freemium product generates vast volumes of data, but using that data to maximize conversion, boost retention, and deliver revenue can be challenging if you don't fully understand the impact that small changes can have on revenue. In this book, author Eric Seufert provides clear guidelines for using data and analytics through all stages of development to optimize your implementation of the freemium model. Freemium Economics de-mystifies the freemium model through an exploration of its core, dataoriented tenets, so that you can apply it methodically rather than hoping that conversion and revenue will naturally follow product launch. By reading Freemium Economics, you will: Learn how to apply data science and big data principles in freemium product design and development to maximize conversion, boost retention, and deliver revenue Gain a broad introduction to the conceptual economic pillars of freemium and a complete understanding of the unique approaches needed to acquire users and convert them from free to paying customers Get practical tips and analytical guidance to successfully implement the freemium model Understand the metrics and infrastructure required to measure the success of a freemium product and improve it post-launch Includes a detailed explanation of the lifetime customer value (LCV) calculation and step-by-step instructions for implementing key performance indicators in a simple, universally-accessible tool like Excel

Open-Source Electronics Platforms Trung Dung Ngo,2019-05-20 Open-source electronics are becoming very popular, and are integrated with our daily educational and developmental activities. At present, the use open-source electronics for teaching science, technology, engineering, and mathematics (STEM) has become a global trend. Off-the-shelf embedded electronics such as Arduino- and Raspberry-compatible modules have been widely used for various applications, from do-it-yourself (DIY) to industrial projects. In addition to the growth of open-source software platforms, open-source electronics play an important role in narrowing the gap between prototyping and product development. Indeed, the technological and social impacts of open-source electronics in teaching, research, and innovation have been widely recognized.

Autonomy and Artificial Intelligence: A Threat or Savior? W.F. Lawless, Ranjeev Mittu, Donald Sofge, Stephen Russell, 2017-08-24 This book explores how Artificial Intelligence (AI), by leading to an increase in the autonomy of machines and robots, is offering opportunities for an expanded but uncertain impact on society by humans, machines, and robots. To help readers better understand the relationships between AI, autonomy, humans and machines that will help society reduce human errors in the use of advanced technologies (e.g., airplanes, trains, cars), this edited volume presents a wide selection of the underlying theories, computational models, experimental methods, and field applications. While other literature deals with these topics individually, this book unifies the fields of autonomy and AI, framing them in the broader context of effective integration for human-autonomous machine and robotic systems. The contributions, written by world-class researchers and scientists, elaborate on key research topics at the heart of effective human-machine-robot-systems integration. These topics include, for example, computational support for intelligence analyses; the challenge of verifying today's and future autonomous systems; comparisons between today's machines and autism; implications of human information interaction on artificial intelligence and errors; systems that reason; the autonomy of machines, robots, buildings; and hybrid teams, where hybrid reflects arbitrary combinations of humans, machines and robots. The contributors span the field of autonomous systems research, ranging from industry and academia to government. Given the broad diversity of the research in this book, the editors strove to thoroughly examine the challenges and trends of systems that implement and exhibit AI; the social implications of present and future systems made autonomous with AI; systems with AI

seeking to develop trusted relationships among humans, machines, and robots; and the effective human systems integration that must result for trust in these new systems and their applications to increase and to be sustained.

Artificial Intelligence and Games Georgios N. Yannakakis, Julian Togelius, 2018-02-17 This is the first textbook dedicated to explaining how artificial intelligence (AI) techniques can be used in and for games. After introductory chapters that explain the background and key techniques in AI and games, the authors explain how to use AI to play games, to generate content for games and to model players. The book will be suitable for undergraduate and graduate courses in games, artificial intelligence, design, human-computer interaction, and computational intelligence, and also for self-study by industrial game developers and practitioners. The authors have developed a website (http://www.gameaibook.org) that complements the material covered in the book with upto-date exercises, lecture slides and reading.

Introduction to Information Systems R. Kelly Rainer, Efraim Turban, 2008-01-09 WHATS IN IT FOR ME? Information technology lives all around us-in how we communicate, how we do business, how we shop, and how we learn. Smart phones, iPods, PDAs, and wireless devices dominate our lives, and yet it's all too easy for students to take information technology for granted. Rainer and Turban's Introduction to Information Systems, 2nd edition helps make Information Technology come alive in the classroom. This text takes students where IT lives-in today's businesses and in our daily lives while helping students understand how valuable information technology is to their future careers. The new edition provides concise and accessible coverage of core IT topics while connecting these topics to Accounting, Finance, Marketing, Management, Human resources, and Operations, so students can discover how critical IT is to each functional area and every business. Also available with this edition is WileyPLUS - a powerful online tool that provides instructors and students with an integrated suite of teaching and learning resources in one easy-to-use website. The WileyPLUS course for Introduction to Information Systems, 2nd edition includes animated tutorials in Microsoft Office 2007, with iPod content and podcasts of chapter summaries provided by author Kelly Rainer.

Metareasoning Michael T. Cox, Anita Raja, 2011 Experts report on the latest artificial intelligence research concerning reasoning about reasoning itself.

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