Pino The Humanoid

Andreas Birk, Silvia Coradeschi, Satoshi Tadokoro

RoboCup 2000: Robot Soccer World Cup IV Peter Stone, Tucker Balch, Gerhard Kraetzschmar, 2003-06-29 This book is the fourth offical archival publication devoted to RoboCup and documents the achievements presented at the Fourth Robot World Cup Soccer Games and Conferences, RoboCup 2000, held in Melbourne, Australia, in August/September 2000. The book presents the following parts: introductory overview and survey, championship papers by the winners of the competitions, finalist papers for the RoboCup challenge awards, papers and posters presented at the workshop, team description of a large number of participating teams. This book is mandatory reading for the rapidly growing RoboCup community as well as a valuable source of reference and inspiration for R & D professionals interested in multi-agent systems, distributed artificial intelligence, and intelligent robotics.

RoboCup 2001: Robot Soccer World Cup V Andreas Birk, Silvia Coradeschi, Satoshi Tadokoro, 2003-08-02 This book is the fifth official archival publication devoted to RoboCup. It documents the achievements presented at the 5th Robot World Cup Soccer Games and Conferences held in Seattle, Washington, USA, in August 2001. The book contains the following parts: introduction, champion teams, challenge award finalists, technical papers, poster presentations, and team descriptions (arranged according to various leagues). This book is mandatory reading for the rapidly growing RoboCup community as well as a valuable source of references and inspiration for R&D professionals interested in multi-agent systems, distributed artificial intelligence, and intelligent robotics.

Humanoid Robots Matthias Hackel,2007-06-01 In this book the variety of humanoid robotic research can be obtained. This book is divided in four parts: Hardware Development: Components and Systems, Biped Motion: Walking, Running and Selforientation, Sensing the Environment: Acquisition, Data Processing and Control and Mind Organisation: Learning and Interaction. The first part of the book deals with remarkable hardware developments, whereby complete humanoid robotic systems are as well described as partial solutions. In the second part diverse results around the biped motion of humanoid robots are presented. The autonomous, efficient and adaptive two-legged walking is one of the main challenge in humanoid robotics. The two-legged walking will enable humanoid robots to enter our environment without rearrangement. Developments in the field of visual sensors, data acquisition, processing and control are to be observed in third part of the book. In the fourth part some mind building and communication technologies are presented.

RoboCup 2002: Robot Soccer World Cup VI Gal A. Kaminka, Pedro U. Lima, Raul Rojas, 2003-11-11 RoboCup 2002, the 6th Robot World Cup Soccer and Rescue Competitions and Conference, took place during June 19-25, 2002, at the Fukuoka Dome (main venue) in Fukuoka, Japan. It was, by far, the RoboCup event with the

largestnumberofregisteredparticipants(1004persons, distributedin188teams from 29 countries) and visitors (around 120,000 persons). As was done in its previous editions since 1997, the event included several robotic competitions and aninternationalsymposium.Thepapersandposterspresen tedatthesymposium

constitutethemainpartofthisbook.Leaguereportsinthe ?nalsectiondescribe signi?cant advances in each league and the results. The symposium organizers received 76 submissions, among which 17 papers (22%) were accepted for oral presentation at the symposium (?rst section of the book), and 21 papers (29%) were accepted as posters (second section of the book). Most papers were evaluated by three reviewers each, chosen from the members of the International Program Committee (IPC). The IPC consisted of a balanced combination of regular RoboCup participants and researchers from outside this community. The reviewers worked hard to guarantee a fair review process - the result of their work was a high-quality symposium with very - teresting presentations.

Intelligent Robotics Systems: Inspiring the NEXT Kairuddin Omar, Md. Jan Nordin, Prahlad Vadakkepat, Anton Satria Prabuwono, Siti Norul Huda Sheikh Abdullah, Jacky Baltes, Shamsudin Mohd Amin, Wan Zuha Wan Hassan, Mohammad Faidzul Nasrudin, 2013-08-16 This book constitutes the refereed proceedings of the 16th FIRA Robo World Congress, FIRA 2013, held in Kuala Lumpur, Malaysia, in August 2013. The congress consisted of the following three conferences: 5th International Conference on Advanced Humanoid Robotics Research (ICAHRR), 5th International Conference on Education and Entertainment Robotics (ICEER), and 4th International Robotics Education Forum (IREF). The 38 revised full papers presented were carefully reviewed and selected from 112 submissions. They cover various topics related to the technical developments and achievements in the field of robotics.

RoboCup 2003: Robot Soccer World Cup VII Daniel Polani, Brett Browning, Andrea Bonarini, Kazuo Yoshida, 2004-08-12 This book constitutes the seventh official archival publication devoted to RoboCup. It documents the achievements presented at the 7th Robot World Cup Soccer and Rescue Competition and Conferences held in Padua, Italy, in July 2003. The 39 revised full papers and 35 revised poster papers presented together with an overview and roadmap for the RoboCup initiative and 3 invited papers were carefully reviewed and selected from 125 symposium paper submissions. This book is mandatory reading for the rapidly growing RoboCup community as well as a valuable source of reference and inspiration for R&D professionals interested in robotics, distributed artificial intelligence, and multi-agent systems.

Design and Control of Intelligent Robotic Systems Dikai Liu, Lingfeng Wang, Kay Chen Tan, 2009-01-22 With the increasing applications of intelligent robotic systems in various ?elds, the - sign and control of these systems have increasingly attracted interest from researchers. This edited book entitled "Design and Control of Intelligent Robotic Systems" in the book series of "Studies in Computational Intelligence" is a collection of some advanced research on design and control of intelligent robots. The works presented range in scope from design methodologies to robot development. Various design approaches and alrithms, such as evolutionary computation, neural networks, fuzzy logic, learning, etc. are included. We also would like to mention that most studies reported in this book have been implemented in physical systems. An overview on the applications of computational intelligence in bio-inspired robotics is given in Chapter 1 by M. Begum and F. Karray, with highlights of the recent progress in bio-inspired robotics research and a focus on the usage of computational intelligence tools to design human-like cognitive abilities in the robotic systems. In Chapter 2, Lisa L. Grant and Ganesh K. Venayagamoorthy present greedy search, particle swarm optimization and fuzzy logic based strategies for navigating a swarm of robots for target search in a hazardous environment, with potential applications in highrisk tasks such as disaster recovery and hazardous material detection.

International e-Conference of Computer Science 2006 Theodore Simos, Georgios Psihoyios, 2007-04-30 Lecture Series on Computer and on Computational Sciences (LSCCS) aims to provide a medium for the publication of new results and developments of high-level research and education in the field of computer and computational science. In this series, only selected proceedings of conferences in all areas of computer science and computational sciences will be published. All publications are aimed at top researchers in the field and all papers in the proceedings volumes will be strictly peer reviewed. The series aims to cover the following areas of computer and computational sciences: Computer Science Hardware Computer Systems Organization Software Data Theory of Computation Mathematics of Computing Information Systems Computing Methodologies Computer Applications Computing Milieu Computational Sciences Computational Mathematics, Theoretical and Computational Physics, Theoretical and Computational Chemistry Scientific Computation Numerical and Computational Algorithms, Modeling and Simulation of Complex System, Web-Based Simulation and Computing, Grid-Based Simulation and Computing Fuzzy Logic, Hybrid Computational Methods, Data Mining and Information Retrieval and Virtual Reality, Reliable Computing, Image Processing, Computational Science and Education

RoboCup 2004: Robot Soccer World Cup VIII Daniele Nardi, Martin Riedmiller, Claude Sammut, José Santos-Victor, 2005-03-01

ThesearetheproceedingsoftheRoboCup2004Symposium, he ldattheInstituto Superior T´ ecnico, in Lisbon, Portugal in conjunction with the RoboCup cpetition. The papers presented here document the many innovations in robotics that result from RoboCup. A problem in any branch of science or engineering is how to devise tests that can provide objective comparisons between alt- native methods. In recent years, competitive engineering challenges have been established to motivate researchers to tackle di?cult problems while providing a framework for the comparison of results. RoboCup was one of the ?rst such competitions and has been a model for the organization of challenges foll- ing sound scienti?c principles. In addition to the competition, the associated symposium provides a forum for researchers to present refereed papers. But, for RoboCup, the symposium has the greater goal of encouraging the exchange of ideas between teams so that the competition, as a whole, progresses from year to year and strengthens its contribution to robotics. One hundred and eighteen papers were submitted to the Symposium. Each paper was reviewed by at least two international referees; 30 papers were - cepted for presentation at the Symposium as full papers and a further 38 were accepted for poster presentation. The quality of the Symposium could not be maintained without the support of the authors and the generous assistance of the referees.

Climbing and Walking Robots and the Support Technologies for Mobile Machines Phillippe Bidaud, Faiz Ben Amar, 2002-11-08 Robotic technology advances for a wide variety of applications Climbing and Walking Robots and the Support Technologies for Mobile Machines explores the increasing interest in real-world robotics and the surge in research and invention it has inspired. Featuring the latest advances from leading robotics labs around the globe, this book presents solutions for perennial challenges in robotics and suggests directions for future research. With applications ranging from personal services and entertainment to emergency rescue and extreme environment intervention, the groundbreaking work presented here provides a glimpse of the future.

Computer Aided Systems Theory - EUROCAST 2003 Robeto Moreno Diaz,2003-10-13 This book constitutes the thoroughly refereed postproceedings of the 9th International Workshop on Computer Aided Systems Theory, EUROCAST 2003, held in Las Palmas de Gran Canaria, Spain in February 2003. The 60 revised full papers presented were carefully selected during two rounds of reviewing and improvement. The papers are organized in topical sections on complex systems tools and applications, logic and formal tools, social and intelligent systems, distributed computing, autonomous and control systems, computational methods in bioinformatics, natural and artificial neural networks, neuroinformatics and neuroimaging, and image processing.

<u>RoboCup</u> ... ,2003

Artificial Neural Nets. Problem Solving Methods José Mira, José R. Alvarez, 2003-08-03 The twovolume set LNCS 2686 and LNCS 2687 constitute the refereed proceedings of the 7th International Work-Conference on Artificial and Natural Neural Networks, IWANN 2003, held in Maã3, Menorca, Spain in June 2003. The 197 revised papers presented were carefully reviewed and selected for inclusion in the book and address the following topics: mathematical and computational methods in neural modelling, neurophysiological data analysis and modelling, structural and functional models of neurons, learning and other plasticity phenomena, complex systems dynamics, cognitive processes and artificial intelligence, methodologies for net design, bio-inspired systems and engineering, and applications in a broad variety of fields.nbsp;

Climbing and Walking Robots Karsten Berns, Rudiger Dillmann, 2001-11-28 Recent advances in robot technology from around the world Climbing and Walking Robots: From Biology to Industrial Applications is a collection of papers presented at the 2001 CLAWAR conference. Featuring current work from leading robotics labs around the globe, this book presents the latest in robotics across industries and suggests directions for future research. Topics include design methodology, bipedal locomotion, fluid actuators, sensor systems, control architecture and simulation, and more. Relevant to mechanical engineers and robotics specialists in both industry and academia, these papers showcase the field's latest technological advances.

Autonomous Robots George A. Bekey, 2005-05-20 An introduction to the science and practice of autonomous robots that reviews over 300 current systems and examines the underlying technology. Autonomous robots are intelligent machines capable of performing tasks in the world by themselves, without explicit human control. Examples range from autonomous helicopters to Roomba, the robot vacuum cleaner. In this book, George Bekey offers an introduction to the science and practice of autonomous robots that can be used both in the classroom and as a reference for industry professionals. He surveys the hardware implementations of more than 300 current systems, reviews some of their application areas, and examines the underlying technology, including control, architectures, learning, manipulation, grasping, navigation, and mapping. Living systems can be considered the prototypes of autonomous systems, and Bekey explores the biological inspiration that forms the basis of many recent developments in robotics. He also discusses robot control issues and the design of control architectures. After an overview of the field that introduces some of its fundamental concepts, the book presents background material on hardware, control (from both biological and engineering perspectives), software architecture, and robot intelligence. It then examines a broad range of implementations and applications, including locomotion (wheeled, legged, flying, swimming, and crawling robots), manipulation (both arms and hands), localization, navigation, and mapping. The many case studies and specific applications include robots built for research, industry, and

the military, among them underwater robotic vehicles, walking machines with four, six, and eight legs, and the famous humanoid robots Cog, Kismet, ASIMO, and QRIO. The book concludes with reflections on the future of robotics-the potential benefits as well as the possible dangers that may arise from large numbers of increasingly intelligent and autonomous robots.

Climbing and Walking Robots M. Osman Tokhi, G.S. Virk, M. Alamgir Hossain, 2006-05-05 The interest in climbing and walking robots (CLAWAR) has intensified in recent years, and novel solutions for complex and very diverse applications have been anticipated by means of significant progress in this area of - botics. Moreover, the amalgamation of original ideas and related innotions, search for new potential applications and the use of state of the art support technologies permit to foresee an important step forward and a significant socio-economic impact of advanced robot technology in the - ture. This is leading to the creation and consolidation of a mobile service robotics sector where most of the robotics activities are foreseen in the - ture. The technology is now maturing to become of real benefit to society and methods of realizing this potential quickly are being eagerly explored. Robot standards and modularity are key to this and form key components of the research presented here. CLAWAR 2005 is the eighth in a series of international conferences - ganised annually since 1998 with the aim to report on latest research and development findings and to provide a forum for scientific discussion and debate within the mobile service robotics community. The series has grown in its popularity significantly over the years, and has attracted - searchers and developers from across the globe. The CLAWAR 2005 p- ceedings reports state of the art scientific and developmental findings p- sented during the CLAWAR

2005 conference in 131 technical presentations by authors from 27 countries covering the five continents.

 $\underline{\rm HWM}$,2005-05 Singapore's leading tech magazine gives its readers the power to decide with its informative articles and in-depth reviews.

Knowledge-based Software Engineering Vadim Stefanuk, Kenji Kaijiri, 2004 JCKBSE aims to provide a forum for researchers and practitioners to discuss the latest developments in the areas of knowledge engineering and software engineering. Particular emphasis is placed upon applying knowledge-based methods to software engineering problems. This volume is a collection of contributions of authors from 8 different countries. The book covers a wide range of topics related to knowledge-based or automated software engineering. architecture of knowledge; software and information systems; requirement engineering; domain analysis and modelling; formal and semiformal specifications; knowledge engineering for domain modelling; data mining and knowledge discovery; automating software design and synthesis; object-oriented and other programming paradigms; knowledge-based methods and tools for software engineering, including testing, verification and validation; process management, maintenance and evolution, applied semiotics for knowledge-based software engineering; knowledge systems methodology; development tools and environments; practical applications and experience of software and knowledge engineering; information technology in control, design, production, logistics and management; enterprise modelling and workflow.

DK Eyewitness Books: Robot Roger Bridgman,2004-03-01 Take a detailed look at the fascinating world of robots - from the earliest single-task machines to the advanced intelligence of robots with feelings. Young readers will be amazed to learn all that robots can do: perform delicate surgical operations, clean city sewers, work as museum tour guides, or even battle each other in combat. Find out how humans have created these mechanical minds and bodies. The most trusted nonfiction series on the market, Eyewitness Books provide an in-depth, comprehensive look at their subjects with a unique integration of words and pictures.

The Coming Robot Revolution Yoseph Bar-Cohen, David Hanson, 2009-04-20 Making a robot that looks and behaves like a human being has been the subject of many popular science fiction movies and books. Although the development of such a robot facesmanychallenges, the making of a virtual human has lon gbeenpotentiallypossible. With recent advances in various key technologies related to hardware and software, the making of humanlike robots is increasingly becoming an engineering reality. Development of the required hardware that can perform humanlike functions in a lifelike manner has benefitted greatly from development in such technologies as biologically inspired materials, artificial intelligence, artificial vision, and many others. Producing a humanlike robot that makes body and facial expressions, communicates verbally using extensive vocabulary, and interprets speech with high accuracy is ext- mely complicated to engineer. Advances in voice recognition and speech synthesis are increasingly improving communication capabilities. In our daily life we encounter such innovations when we call the telephone operators of most companies today. As robotics technology continues to improve we are approaching the point where, on seeing such a robot, we will respond with "Wow, this robot looks unbelievably real!'' just like the reaction to an artificial flower. The accelerating pace of advances in related fields suggests that the emergence of humanlike robots that become part of

our daily life seems to be imminent. These robots are expected to raise ethical concerns and may also raise many complex questions related to their interaction with humans.

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