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**Roberto Di Pietro, Simone Raponi, Maurantonio
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Time-Critical Cooperative Control of Autonomous Air Vehicles Isaac Kaminer,António M.

Pascoal,Enric Xargay,Naira Hovakimyan,Venanzio Cichella,Vladimir Dobrokhodov,2017-08-02 Time-Critical Cooperative Control of Autonomous Air Vehicles presents, in an easy-to-read style, the latest research conducted in the industry, while also introducing a set of novel ideas that illuminate a new approach to problem-solving. The book is virtually self-contained, giving the reader a complete, integrated presentation of the different concepts, mathematical tools, and control solutions needed to tackle and solve a number of problems concerning time-critical cooperative control of UAVs. By including case studies of fixed-wing and multirotor UAVs, the book effectively broadens the scope of application of the methodologies developed. This theoretical presentation is complemented with the results of flight tests with real UAVs, and is an ideal reference for researchers and practitioners from academia, research labs, commercial companies, government workers, and those in the international aerospace industry. Addresses important topics related to time-critical cooperative control of UAVs Describes solutions to the problems rooted in solid dynamical systems theory Applies the solutions developed to fixed-wing and multirotor UAVs Includes the results of field tests with both classes of UAVs

New Dimensions of Information Warfare Roberto Di Pietro,Simone Raponi,Maurantonio Caprolu,Stefano Cresci,2020-12-03 This book revises the strategic

objectives of Information Warfare, interpreting them according to the modern canons of information age, focusing on the fabric of society, the economy, and critical Infrastructures. The authors build plausible detailed real-world scenarios for each entity, showing the related possible threats from the Information Warfare point of view. In addition, the authors dive into the description of the still open problems, especially when it comes to critical infrastructures, and the countermeasures that can be implemented, possibly inspiring further research in the domain. This book intends to provide a conceptual framework and a methodological guide, enriched with vivid and compelling use cases for the readers (e.g. technologists, academicians, military, government) interested in what Information Warfare really means, when its lenses are applied to current technology. Without sacrificing accuracy, rigor and, most importantly, the big picture of Information Warfare, this book dives into several relevant and up-to-date critical domains. The authors illustrate how finance (an always green target of Information Warfare) is intertwined with Social Media, and how an opponent could exploit these latter ones to reach its objectives. Also, how cryptocurrencies are going to reshape the economy, and the risks involved by this paradigm shift. Even more compelling is how the very fabric of society is going to be reshaped by technology, for instance how our democratic elections are exposed to risks that are even greater than what appears in the current public discussions. Not to mention how our Critical Infrastructure is

becoming exposed to a series of novel threats, ranging from state-supported malware to drones. A detailed discussion of possible countermeasures and what the open issues are for each of the highlighted threats complete this book. This book targets a widespread audience that includes researchers and advanced level students studying and working in computer science with a focus on security. Military officers, government officials and professionals working in this field will also find this book useful as a reference.

I Know Why the Caged Bird Sings Maya

Angelou, 2010-07-21 Here is a book as joyous and painful, as mysterious and memorable, as childhood itself. *I Know Why the Caged Bird Sings* captures the longing of lonely children, the brute insult of bigotry, and the wonder of words that can make the world right. Maya Angelou's debut memoir is a modern American classic beloved worldwide. Sent by their mother to live with their devout, self-sufficient grandmother in a small Southern town, Maya and her brother, Bailey, endure the ache of abandonment and the prejudice of the local "powhitetrash." At eight years old and back at her mother's side in St. Louis, Maya is attacked by a man many times her age—and has to live with the consequences for a lifetime. Years later, in San Francisco, Maya learns that love for herself, the kindness of others, her own strong spirit, and the ideas of great authors ("I met and fell in love with William Shakespeare") will allow her to be free instead of imprisoned. Poetic and powerful, *I Know Why the Caged Bird Sings* will touch hearts and change minds for as long as people read. "I

Know Why the Caged Bird Sings liberates the reader into life simply because Maya Angelou confronts her own life with such a moving wonder, such a luminous dignity.”—James Baldwin From the Paperback edition.

Template Matching Techniques in Computer Vision
Roberto Brunelli, 2009-04-29 The detection and recognition of objects in images is a key research topic in the computer vision community. Within this area, face recognition and interpretation has attracted increasing attention owing to the possibility of unveiling human perception mechanisms, and for the development of practical biometric systems. This book and the accompanying website, focus on template matching, a subset of object recognition techniques of wide applicability, which has proved to be particularly effective for face recognition applications. Using examples from face processing tasks throughout the book to illustrate more general object recognition approaches, Roberto Brunelli: examines the basics of digital image formation, highlighting points critical to the task of template matching; presents basic and advanced template matching techniques, targeting grey-level images, shapes and point sets; discusses recent pattern classification paradigms from a template matching perspective; illustrates the development of a real face recognition system; explores the use of advanced computer graphics techniques in the development of computer vision algorithms. *Template Matching Techniques in Computer Vision* is primarily aimed at practitioners working on the development of systems for effective object

recognition such as biometrics, robot navigation, multimedia retrieval and landmark detection. It is also of interest to graduate students undertaking studies in these areas.

How to Analyze the Cyber Threat from Drones

Katharina Ley Best, Jon Schmid, Shane Tierney, 2020-04-30 The authors explore approaches for understanding, inventorying, and modeling cyber security implications of unmanned aerial systems (drones), and examine the threats and trends around them--specifically, current vulnerabilities and future trends.

Man, Play, and Games Roger Caillois, 2001

According to Roger Caillois, play is an occasion of pure waste. In spite of this - or because of it - play constitutes an essential element of human social and spiritual development. In this study, the author defines play as a free and voluntary activity that occurs in a pure space, isolated and protected from the rest of life.

Building Your Own Drones John

Baichtal, 2015-08-25 Absolutely no experience needed! Build your drone, step-by-step, with this full-color, hands-on guide! You've heard about drones. You've seen drones. Now, build your own—it's a lot easier than you think! Drones are the newest frontier for the DIY/maker community, and you don't need to be a technical expert to build one. John Baichtal, the #1 author of hardware hacking books for beginners, will teach you all the skills you need. First, Baichtal shows you the amazing drones others have built. Then, he walks you through several complete projects: quadcopters, UAVs, ROVs, and more. Not ready to

start from scratch? No problem: Baichtal helps you choose from today's best new kits. Hundreds of full-color step-by-step photos teach you every step, every skill. When you're ready for more advanced concepts, Baichtal explains them in plain English. Discover what drones are and why they're so exciting Explore today's most imaginative projects, from 3D-printed mini quadcopters to floating robot armies Compare kits, from \$200 up: Parallax ELEV-8, DJI Phantom 2 Vision+, OpenROV, Actobotics Nomad, Brooklyn Aerodrome Flack, and more Create your own practical Drone Builder's Workbench Build complete rocket, blimp, waterborne, and automotive drones Construct both fully autonomous and radio-controlled drones Choose and assemble your chassis (airframe), motor, props, flight control, power system, accessories, and software Integrate Arduino to make radio-controlled drones operate autonomously Teach a drone to navigate via RFID tags Learn all the basic electronics and programming you'll need

The Future of Drone Use Bart Custers, 2016-10-15
Given the popularity of drones and the fact that they are easy and cheap to buy, it is generally expected that the ubiquity of drones will significantly increase within the next few years. This raises questions as to what is technologically feasible (now and in the future), what is acceptable from an ethical point of view and what is allowed from a legal point of view. Drone technology is to some extent already available and to some extent still in development. The aim and scope of this book is to map the opportunities and threats associated with the use

of drones and to discuss the ethical and legal issues of the use of drones. This book provides an overview of current drone technologies and applications and of what to expect in the next few years. The question of how to regulate the use of drones in the future is addressed, by considering conditions and contents of future drone legislation and by analyzing issues surrounding privacy and safeguards that can be taken. As such, this book is valuable to scholars in several disciplines, such as law, ethics, sociology, politics and public administration, as well as to practitioners and others who may be confronted with the use of drones in their work, such as professionals working in the military, law enforcement, disaster management and infrastructure management. Individuals and businesses with a specific interest in drone use may also find in the nineteen contributions contained in this volume unexpected perspectives on this new field of research and innovation. Bart Custers is Associate Professor and Head of Research at eLaw, the Center for Law and Digital Technologies at Leiden University, The Netherlands. He has presented his work at international conferences in the United States, China, Japan, the Middle East and throughout Europe and has published over 80 scientific, professional and popularizing publications, including three books.

Drones George Dekoulis, 2018-06-27 Drone technologies have constantly been developing for over 100 years. The latest models exhibit a previously unseen set of specifications available

to the end users. The collective effort of distinguished international researchers, within the field of drone technologies, has been incorporated into this textbook suitable to the broader audience. The book has been edited by Prof. George Dekoulis, Aerospace Engineering Institute (AEI), Cyprus, an expert on state-of-the-art implementations of reconfigurable space engineering systems. The book consists of four main sections, namely, Introduction, Drone History, Drone Design, and Drone Applications. We hope this book will be beneficial to professionals, researchers, and academicians and, moreover, to inspire the younger generations into pursuing relevant academic studies and professional careers within the drone industry.

Air Force Combat Units of World War II Maurer Maurer, 1961

Experimental Robotics VIII Bruno Siciliano, Paolo Dario, 2003-01-21 This book is a collection of papers on the state of the art in experimental robotics. Experimental Robotics is at the core of validating robotics research for both its systems science and theoretical foundations. Because robotics experiments are carried out on physical, complex machines, of which its controllers are subject to uncertainty, devising meaningful experiments and collecting statistically significant results, pose important and unique challenges in robotics. Robotics experiments serve as a unifying theme for robotics system science and algorithmic foundations. These observations have led to the creation of the International Symposia on Experimental Robotics. The papers in

this book were presented at the 2002 International Symposium on Experimental Robotics.

Los Angeles Magazine ,2003-11 Los Angeles magazine is a regional magazine of national stature. Our combination of award-winning feature writing, investigative reporting, service journalism, and design covers the people, lifestyle, culture, entertainment, fashion, art and architecture, and news that define Southern California. Started in the spring of 1961, Los Angeles magazine has been addressing the needs and interests of our region for 48 years. The magazine continues to be the definitive resource for an affluent population that is intensely interested in a lifestyle that is uniquely Southern Californian.

Process Control Myke King,2016-07-12 This expanded new edition is specifically designed to meet the needs of the process industry, and closes the gap between theory and practice. Back-to-basics approach, with a focus on techniques that have an immediate practical application, and heavy maths relegated to the end of the book Written by an experienced practitioner, highly regarded by major corporations, with 25 years of teaching industry courses Supports the increasing expectations for Universities to teach more practical process control (supported by IChemE)

The Educated Mind Kieran Egan,2007-12-01 The Educated Mind offers a bold and revitalizing new vision for today's uncertain educational system. Kieran Egan reconceives education, taking into account how we learn. He proposes the use of particular intellectual tools—such as language or

literacy—that shape how we make sense of the world. These mediating tools generate successive kinds of understanding: somatic, mythic, romantic, philosophical, and ironic. Egan's account concludes with practical proposals for how teaching and curriculum can be changed to reflect the way children learn. A carefully argued and readable book. . . . Egan proposes a radical change of approach for the whole process of education. . . . There is much in this book to interest and excite those who discuss, research or deliver education.—Ann Fullick, *New Scientist* A compelling vision for today's uncertain educational system.—*Library Journal* Almost anyone involved at any level or in any part of the education system will find this a fascinating book to read.—Dr. Richard Fox, *British Journal of Educational Psychology* A fascinating and provocative study of cultural and linguistic history, and of how various kinds of understanding that can be distinguished in that history are recapitulated in the developing minds of children.—Jonty Driver, *New York Times Book Review*

JavaScript for Kids Nick Morgan, 2014-12-14
JavaScript is the programming language of the Internet, the secret sauce that makes the Web awesome, your favorite sites interactive, and online games fun! *JavaScript for Kids* is a lighthearted introduction that teaches programming essentials through patient, step-by-step examples paired with funny illustrations. You'll begin with the basics, like working with strings, arrays, and loops, and then move on to more advanced topics, like building interactivity with jQuery and

drawing graphics with Canvas. Along the way, you'll write games such as Find the Buried Treasure, Hangman, and Snake. You'll also learn how to: –Create functions to organize and reuse your code –Write and modify HTML to create dynamic web pages –Use the DOM and jQuery to make your web pages react to user input –Use the Canvas element to draw and animate graphics –Program real user-controlled games with collision detection and score keeping With visual examples like bouncing balls, animated bees, and racing cars, you can really see what you're programming. Each chapter builds on the last, and programming challenges at the end of each chapter will stretch your brain and inspire your own amazing programs. Make something cool with JavaScript today! Ages 10+ (and their parents!)

Drones for Biodiversity Conservation and Ecological Monitoring Ricardo Díaz-Delgado, Sander Múcher, 2019-12-18 Unmanned aerial vehicles (UAV) have already become an affordable and cost-efficient tool to quickly map a targeted area for many emerging applications in the arena of ecological monitoring and biodiversity conservation. Managers, owners, companies, and scientists are using professional drones equipped with high-resolution visible, multispectral, or thermal cameras to assess the state of ecosystems, the effect of disturbances, or the dynamics and changes within biological communities inter alia. We are now at a tipping point on the use of drones for these type of applications over natural areas. UAV missions are increasing but most of them are testing applicability. It is time now to move to

frequent revisiting missions, aiding in the retrieval of important biophysical parameters in ecosystems or mapping species distributions. This Special Issue shows UAV applications contributing to a better understanding of biodiversity and ecosystem status, threats, changes, and trends. It documents the enhancement of knowledge in ecological integrity parameters mapping, long-term ecological monitoring based on drones, mapping of alien species spread and distribution, upscaling ecological variables from drone to satellite images: methods and approaches, rapid risk and disturbance assessment using drones, mapping albedo with UAVs, wildlife tracking, bird colony and chimpanzee nest mapping, habitat mapping and monitoring, and a review on drones for conservation in protected areas.

Drones in Smart-Cities Fadi Al-

Turjman, 2020-06-04 *Drones in Smart-Cities: Security and Performance* is the first book dedicated to drones in smart cities, helping address the many research challenges in bringing UAVs into practice. The book incorporates insights from the latest research in Internet of Things, big data, and cloud computing, 5G, and other communication technologies. It examines the design and implementation of UAV, focusing on data delivery, performability, and security. Intended for researchers, engineers, and practitioners, *Drones in Smart-Cities: Security and Performance* combines the technical aspects with academic theory to help implement the smart city vision around the globe. Addresses UAV and IoT for smart cities applications Examines topics as UAV safety,

challenges, localization methods. QoS, simulation tools, and more Collect the relevant knowledge in one resource, saving research time and effort

Proceedings of the 4th International Conference on Electrical Engineering and Control Applications

Sofiane Bououden, Mohammed Chadli, Salim Ziani, Ivan Zelinka, 2020-09-29 This book gathers papers presented during the 4th International Conference on Electrical Engineering and Control Applications. It covers new control system models, troubleshooting tips and complex system requirements, such as increased speed, precision and remote capabilities. Additionally, the papers discuss not only the engineering aspects of signal processing and various practical issues in the broad field of information transmission, but also novel technologies for communication networks and modern antenna design. This book is intended for researchers, engineers and advanced postgraduate students in the fields of control and electrical engineering, computer science and signal processing, as well as mechanical and chemical engineering.

Designing for Situation Awareness Mica R.

Endsley, Betty Bolte, Debra G. Jones, 2003-07-17 Enhancing Situation Awareness (SA) is a major design goal for projects in many fields, including aviation, ground transportation, air traffic control, nuclear power, and medicine, but little information exists in an integral format to support this goal. Designing for Situation Awareness helps designers understand how people acquire and interpret information in complex settings and recognize the factors that undermine

this process. Designing to support operator SA reduces the incidence of human error, which has been found to occur largely due to failures in SA. Whereas many previous human factors efforts have focused on design at the perceptual and surface feature level, SA-oriented design focuses on the operator's information needs and cognitive processes as they juggle to integrate information from many sources and achieve multiple competing goals. Thus it addresses design from a system's perspective. By applying theoretical and empirical information on SA to the system design process, human factors practitioners can create designs to support SA across a wide variety of domains and design issues. This book serves as a helpful reference to that end.

ROS Robotics By Example Carol Fairchild, Dr. Thomas L. Harman, 2016-06-30 Bring life to your robot using ROS robotic applications About This Book This book will help you boost your knowledge of ROS and give you advanced practical experience you can apply to your ROS robot platforms This is the only book that offers you step-by-step instructions to solidify your ROS understanding and gain experience using ROS tools From eminent authors, this book offers you a plethora of fun-filled examples to make your own quadcopter, turtlebot, and two-armed robots Who This Book Is For If you are a robotics developer, whether a hobbyist, researchers or professional, and are interested in learning about ROS through a hands-on approach, then this book is for you. You are encouraged to have a working knowledge of GNU/Linux systems and Python. What You Will Learn

Get to know the fundamentals of ROS and apply its concepts to real robot examples
Control a mobile robot to navigate autonomously in an environment
Model your robot designs using URDF and Xacro, and operate them in a ROS Gazebo simulation
Control a 7 degree-of-freedom robot arm for visual servoing
Fly a quadcopter to autonomous waypoints
Gain working knowledge of ROS tools such as Gazebo, rviz, rqt, and Move-It
Control robots with mobile devices and controller boards
In Detail
The visionaries who created ROS developed a framework for robotics centered on the commonality of robotic systems and exploited this commonality in ROS to expedite the development of future robotic systems. From the fundamental concepts to advanced practical experience, this book will provide you with an incremental knowledge of the ROS framework, the backbone of the robotics evolution. ROS standardizes many layers of robotics functionality from low-level device drivers to process control to message passing to software package management. This book provides step-by-step examples of mobile, armed, and flying robots, describing the ROS implementation as the basic model for other robots of these types. By controlling these robots, whether in simulation or in reality, you will use ROS to drive, move, and fly robots using ROS control. Style and approach
This is an easy-to-follow guide with hands-on examples of ROS robots, both real and in simulation.

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