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Karakuri Keisuke Saka,2010-03-16 Japanese paper engineer Hosaka presents instructions for constructing four models: Tea-serving robot, Ready to fly, Peek-a-bear -- Wild Wild West.

Fundamentals of Robotic Mechanical Systems Jorge Angeles,2013-03-09 Mechanical engineering, an engineering discipline borne of the needs of the industrial revolution, is once again asked to do its substantial share in the call for industrial renewal. The general call is urgent as we face profound issues of productivity and competitiveness that require engineering solutions, among others. The Mechanical Engineering Series features graduate texts and research monographs intended to address the need for information in contemporary areas of mechanical engineering. The series is conceived as a comprehensive one that covers a broad range of concentrations important to mechanical engineering graduate education and research. We are fortunate to have a distinguished roster of consulting editors on the advisory board, each an expert in one of the areas of concentration. The names of the consulting editors are listed on the next page of this volume. The areas of concentration are: applied mechanics; biomechanics; computational mechanics; dynamic systems and control; energetics; mechanics of materials; processing; thermal science; and tribology.

Modelling and Control of Robot Manipulators Lorenzo Sciavicco,Bruno Siciliano,2012-12-06 Fundamental and technological topics are blended uniquely and developed clearly in nine chapters with a gradually increasing level of complexity. A wide variety of relevant problems is raised throughout, and the proper tools to find engineering-oriented solutions are introduced and explained, step by step. Fundamental coverage includes: Kinematics; Statics and dynamics of manipulators; Trajectory planning and motion control in free space. Technological aspects include: Actuators; Sensors; Hardware/software control architectures; Industrial robot-control algorithms. Furthermore, established research results involving description of end-effector orientation, closed kinematic chains, kinematic redundancy and singularities, dynamic parameter identification, robust and adaptive control and force/motion control are provided. To provide readers with a homogeneous background, three appendices are included on: Linear algebra; Rigid-body mechanics; Feedback control. To acquire practical skill, more than 50 examples and case studies are carefully worked out and interwoven through the text, with frequent resort to simulation. In addition, more than 80 end-of-chapter exercises are proposed, and the book is accompanied by a solutions manual containing the MATLAB code for computer problems; this is available from the publisher free of charge to those adopting this work as a textbook for courses.

Annals of Scientific Society for Assembly, Handling and Industrial Robotics Thorsten Schüppstuhl,Kirsten Tracht,Dominik Henrich,2020-08-21 This Open Access proceedings present a good overview of the current research landscape of industrial robots. The objective of MHI Colloquium is a successful networking at academic and management level. Thereby the colloquium is focussing on a high level academic exchange to distribute the obtained research results, determine synergetic effects and trends, connect the actors personally and in conclusion strengthen the research field as well as the MHI community. Additionally there is the possibility to become acquainted with the organizing institute. Primary audience are members of the scientific association for assembly, handling and industrial robots (WG MHI).

Deep Learning with Python Francois Chollet,2017-11-30 Summary Deep Learning with Python introduces the field of deep learning using the Python language and the powerful Keras library. Written by Keras creator and Google AI researcher François Chollet, this book builds your understanding through intuitive explanations and practical examples. Purchase of the print book includes a free

eBook in PDF, Kindle, and ePub formats from Manning Publications. About the Technology Machine learning has made remarkable progress in recent years. We went from near-unusable speech and image recognition, to near-human accuracy. We went from machines that couldn't beat a serious Go player, to defeating a world champion. Behind this progress is deep learning—a combination of engineering advances, best practices, and theory that enables a wealth of previously impossible smart applications. About the Book Deep Learning with Python introduces the field of deep learning using the Python language and the powerful Keras library. Written by Keras creator and Google AI researcher François Chollet, this book builds your understanding through intuitive explanations and practical examples. You'll explore challenging concepts and practice with applications in computer vision, natural-language processing, and generative models. By the time you finish, you'll have the knowledge and hands-on skills to apply deep learning in your own projects. What's Inside Deep learning from first principles Setting up your own deep-learning environment Image-classification models Deep learning for text and sequences Neural style transfer, text generation, and image generation About the Reader Readers need intermediate Python skills. No previous experience with Keras, TensorFlow, or machine learning is required. About the Author François Chollet works on deep learning at Google in Mountain View, CA. He is the creator of the Keras deep-learning library, as well as a contributor to the TensorFlow machine-learning framework. He also does deep-learning research, with a focus on computer vision and the application of machine learning to formal reasoning. His papers have been published at major conferences in the field, including the Conference on Computer Vision and Pattern Recognition (CVPR), the Conference and Workshop on Neural Information Processing Systems (NIPS), the International Conference on Learning Representations (ICLR), and others. Table of Contents PART 1 - FUNDAMENTALS OF DEEP LEARNING What is deep learning? Before we begin: the mathematical building blocks of neural networks Getting started with neural networks Fundamentals of machine learning PART 2 - DEEP LEARNING IN PRACTICE Deep learning for computer vision Deep learning for text and sequences Advanced deep-learning best practices Generative deep learning Conclusions appendix A - Installing Keras and its dependencies on Ubuntu appendix B - Running Jupyter notebooks on an EC2 GPU instance

Emerging Trends in Mechatronics Aydin Azizi, 2020-01-15 Mechatronics is a multidisciplinary branch of engineering combining mechanical, electrical and electronics, control and automation, and computer engineering fields. The main research task of mechatronics is design, control, and optimization of advanced devices, products, and hybrid systems utilizing the concepts found in all these fields. The purpose of this special issue is to help better understand how mechatronics will impact on the practice and research of developing advanced techniques to model, control, and optimize complex systems. The special issue presents recent advances in mechatronics and related technologies. The selected topics give an overview of the state of the art and present new research results and prospects for the future development of the interdisciplinary field of mechatronic systems.

Elements of Robotics Mordechai Ben-Ari, Francesco Mondada, 2017-10-25 This open access book bridges the gap between playing with robots in school and studying robotics at the upper undergraduate and graduate levels to prepare for careers in industry and research. Robotic algorithms are presented formally, but using only mathematics known by high-school and first-year college students, such as calculus, matrices and probability. Concepts and algorithms are explained through detailed diagrams and calculations. Elements of Robotics presents an overview of different types of robots and the components used to build robots, but focuses on robotic algorithms: simple algorithms like odometry and feedback control, as well as algorithms for advanced topics like localization, mapping, image processing, machine learning and swarm robotics. These algorithms are demonstrated in simplified contexts that enable detailed

computations to be performed and feasible activities to be posed. Students who study these simplified demonstrations will be well prepared for advanced study of robotics. The algorithms are presented at a relatively abstract level, not tied to any specific robot. Instead a generic robot is defined that uses elements common to most educational robots: differential drive with two motors, proximity sensors and some method of displaying output to the user. The theory is supplemented with over 100 activities, most of which can be successfully implemented using inexpensive educational robots. Activities that require more computation can be programmed on a computer. Archives are available with suggested implementations for the Thymio robot and standalone programs in Python.

Trajectory Planning for Automatic Machines and Robots Luigi Biagiotti, Claudio Melchiorri, 2008-10-23 This book deals with the problems related to planning motion laws and trajectories for the actuation system of automatic machines, in particular for those based on electric drives, and robots. The problem of planning suitable trajectories is relevant not only for the proper use of these machines, in order to avoid undesired effects such as vibrations or even damages on the mechanical structure, but also in some phases of their design and in the choice and sizing of the actuators. This is particularly true now that the concept of “electronic cams” has replaced, in the design of automatic machines, the classical approach based on “mechanical cams”. The choice of a particular trajectory has direct and relevant implications on several aspects of the design and use of an automatic machine, like the dimensioning of the actuators and of the reduction gears, the vibrations and efforts generated on the machine and on the load, the tracking errors during the motion execution. For these reasons, in order to understand and appreciate the peculiarities of the different techniques available for trajectory planning, besides the mathematical aspects of their implementation also a detailed analysis in the time and frequency domains, a comparison of their main properties under different points of view, and general considerations related to their practical use are reported.

Field and Service Robotics Peter Corke, Salah Sukkarieh, 2006-08-03 The 5th International Conference on Field and Service Robotics (FSR05) was held in Port Douglas, Australia, on 29th - 31st July 2005, and brought together the worlds' leading experts in field and service automation. The goal of the conference was to report and encourage the latest research and practical results towards the use of field and service robotics in the community with particular focus on proven technology. The conference provided a forum for researchers, professionals and robot manufacturers to exchange up-to-date technical knowledge and experience. Field robots are robots which operate in outdoor, complex, and dynamic environments. Service robots are those that work closely with humans, with particular applications involving indoor and structured environments. There are a wide range of topics presented in this issue on field and service robots including: Agricultural and Forestry Robotics, Mining and Exploration Robots, Robots for Construction, Security & Defence Robots, Cleaning Robots, Autonomous Underwater Vehicles and Autonomous Flying Robots. This meeting was the fifth in the series and brings FSR back to Australia where it was first held. FSR has been held every 2 years, starting with Canberra 1997, followed by Pittsburgh 1999, Helsinki 2001 and Lake Yamanaka 2003.

Applications of Robotics in Industry Using Advanced Mechanisms Janmenjoy Nayak, Valentina E. Balas, Margarita N. Favorskaya, Bibhuti Bhusan Choudhury, S. Krishna Mohan Rao, Bighnaraj Naik, 2019-09-03 This book shares important findings on the application of robotics in industry using advanced mechanisms, including software and hardware. It presents a collection of recent trends and research on various advanced computing paradigms such as soft computing, robotics, smart automation, power control, and uncertainty analysis. The book constitutes the proceedings of the 1st International Conference on Application of Robotics in Industry using Advanced Mechanisms (ARIAM2019), which offered a platform for sharing original research findings, presenting innovative ideas

and applications, and comparing notes on various aspects of robotics. The contributions highlight the latest research and industrial applications of robotics, and discuss approaches to improving the smooth functioning of industries. Moreover, they focus on designing solutions for complex engineering problems and designing system components or processes to meet specific needs, with due considerations for public health and safety, including cultural, societal, and environmental considerations. Taken together, they offer a valuable resource for researchers, scientists, engineers, professionals and students alike.

Smart Technologies for Precision Assembly Svetan Ratchev, 2021-04-01 This open access book constitutes the refereed post-conference proceedings of the 9th IFIP WG 5.5 International Precision Assembly Seminar, IPAS 2020, held virtually in December 2020. The 16 revised full papers and 10 revised short papers presented together with 1 keynote paper were carefully reviewed and selected from numerous submissions. The papers address topics such as assembly design and planning; assembly operations; assembly cells and systems; human centred assembly; and assistance methods in assembly.

Additive Manufacturing Amit Bandyopadhyay, Susmita Bose, 2015-09-08 The field of additive manufacturing has seen explosive growth in recent years due largely in part to renewed interest from the manufacturing sector. Conceptually, additive manufacturing, or industrial 3D printing, is a way to build parts without using any part-specific tooling or dies from the computer-aided design (CAD) file of the part. Today, mo

The Big Book of Small Python Projects Al Sweigart, 2021-06-25 Best-selling author Al Sweigart shows you how to easily build over 80 fun programs with minimal code and maximum creativity. If you've mastered basic Python syntax and you're ready to start writing programs, you'll find The Big Book of Small Python Projects both enlightening and fun. This collection of 81 Python projects will have you making digital art, games, animations, counting pro- grams, and more right away. Once you see how the code works, you'll practice re-creating the programs and experiment by adding your own custom touches. These simple, text-based programs are 256 lines of code or less. And whether it's a vintage screensaver, a snail-racing game, a clickbait headline generator, or animated strands of DNA, each project is designed to be self-contained so you can easily share it online. You'll create:

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- Encryption programs that use ciphers like ROT13 and Vigenère to conceal text

If you're tired of standard step-by-step tutorials, you'll love the learn-by-doing approach of The Big Book of Small Python Projects. It's proof that good things come in small programs!

Robotic Grasping and Manipulation Yu Sun, Joe Falco, 2018-07-14 This book constitutes the refereed proceedings of the First Robotic Grasping and Manipulation Challenge, RGMC 2016, held at IROS 2016, Daejeon, South Korea, in October 2016. The 13 revised full papers presented were carefully reviewed and are describing the rules, results, competitor systems and future directions of the inaugural competition. The competition was designed to allow researchers focused on the application of robot systems to compare the performance of hand designs as well as autonomous grasping and manipulation solutions across a common set of tasks. The competition was comprised of three tracks that included hand-in-hand grasping, fully autonomous grasping, and simulation.

Artificial Intelligence in Asset Management Söhnke M. Bartram, Jürgen Branke, Mehrshad Motahari, 2020-08-28 Artificial intelligence (AI) has grown in presence in asset management and has revolutionized the sector in many ways. It has improved portfolio management, trading, and risk management practices by increasing efficiency, accuracy, and compliance. In particular, AI techniques

help construct portfolios based on more accurate risk and return forecasts and more complex constraints. Trading algorithms use AI to devise novel trading signals and execute trades with lower transaction costs. AI also improves risk modeling and forecasting by generating insights from new data sources. Finally, robo-advisors owe a large part of their success to AI techniques. Yet the use of AI can also create new risks and challenges, such as those resulting from model opacity, complexity, and reliance on data integrity.

The Vintage Rolex Field Guide Colin A. White,2019-05-01 Does the sheer variety paralyze you? Are you stumped by the acronyms and jargon? Fearful of scammers and just want an honest watch at a fair price? Like you, each watch is unique and matching one to a collection or collector is a special event. Whether it's a first or a last, the match is visceral and life long. There's a lot at stake. The Vintage Rolex Field Guide is your best shot at buying-well and avoiding pitfalls. It is full of advice and details to help you access facts and specs without gushy superlatives. Spot, identify and assess the best vintage Rolex watches with the right data. Life is short and your time is precious so wear it well. If you're ready to take action, this book is for you.

Learning for Adaptive and Reactive Robot Control Aude Billard,Sina Mirrazavi,Nadia Figueroa,2022-02-08 Methods by which robots can learn control laws that enable real-time reactivity using dynamical systems; with applications and exercises. This book presents a wealth of machine learning techniques to make the control of robots more flexible and safe when interacting with humans. It introduces a set of control laws that enable reactivity using dynamical systems, a widely used method for solving motion-planning problems in robotics. These control approaches can replan in milliseconds to adapt to new environmental constraints and offer safe and compliant control of forces in contact. The techniques offer theoretical advantages, including convergence to a goal, non-penetration of obstacles, and passivity. The coverage of learning begins with low-level control parameters and progresses to higher-level competencies composed of combinations of skills. Learning for Adaptive and Reactive Robot Control is designed for graduate-level courses in robotics, with chapters that proceed from fundamentals to more advanced content. Techniques covered include learning from demonstration, optimization, and reinforcement learning, and using dynamical systems in learning control laws, trajectory planning, and methods for compliant and force control . Features for teaching in each chapter: applications, which range from arm manipulators to whole-body control of humanoid robots; pencil-and-paper and programming exercises; lecture videos, slides, and MATLAB code examples available on the author's website . an eTextbook platform website offering protected material[EPS2] for instructors including solutions.

Architects of Intelligence Martin Ford,2018-11-23 Financial Times Best Books of the Year 2018 TechRepublic Top Books Every Techie Should Read Book Description How will AI evolve and what major innovations are on the horizon? What will its impact be on the job market, economy, and society? What is the path toward human-level machine intelligence? What should we be concerned about as artificial intelligence advances? Architects of Intelligence contains a series of in-depth, one-to-one interviews where New York Times bestselling author, Martin Ford, uncovers the truth behind these questions from some of the brightest minds in the Artificial Intelligence community. Martin has wide-ranging conversations with twenty-three of the world's foremost researchers and entrepreneurs working in AI and robotics: Demis Hassabis (DeepMind), Ray Kurzweil (Google), Geoffrey Hinton (Univ. of Toronto and Google), Rodney Brooks (Rethink Robotics), Yann LeCun (Facebook) , Fei-Fei Li (Stanford and Google), Yoshua Bengio (Univ. of Montreal), Andrew Ng (AI Fund), Daphne Koller (Stanford), Stuart Russell (UC Berkeley), Nick Bostrom (Univ. of Oxford), Barbara Grosz (Harvard), David Ferrucci (Elemental Cognition), James Manyika (McKinsey), Judea Pearl (UCLA), Josh Tenenbaum (MIT), Rana el Kaliouby (Affectiva), Daniela Rus (MIT), Jeff Dean (Google), Cynthia Breazeal (MIT), Oren Etzioni (Allen Institute for AI), Gary Marcus (NYU), and Bryan Johnson (Kernel).

Martin Ford is a prominent futurist, and author of Financial Times Business Book of the Year, *Rise of the Robots*. He speaks at conferences and companies around the world on what AI and automation might mean for the future. Meet the minds behind the AI superpowers as they discuss the science, business and ethics of modern artificial intelligence. Read James Manyika's thoughts on AI analytics, Geoffrey Hinton's breakthroughs in AI programming and development, and Rana el Kaliouby's insights into AI marketing. This AI book collects the opinions of the luminaries of the AI business, such as Stuart Russell (coauthor of the leading AI textbook), Rodney Brooks (a leader in AI robotics), Demis Hassabis (chess prodigy and mind behind AlphaGo), and Yoshua Bengio (leader in deep learning) to complete your AI education and give you an AI advantage in 2019 and the future.

Statistical Rethinking Richard McElreath, 2018-01-03 *Statistical Rethinking: A Bayesian Course with Examples in R and Stan* builds readers' knowledge of and confidence in statistical modeling. Reflecting the need for even minor programming in today's model-based statistics, the book pushes readers to perform step-by-step calculations that are usually automated. This unique computational approach ensures that readers understand enough of the details to make reasonable choices and interpretations in their own modeling work. The text presents generalized linear multilevel models from a Bayesian perspective, relying on a simple logical interpretation of Bayesian probability and maximum entropy. It covers from the basics of regression to multilevel models. The author also discusses measurement error, missing data, and Gaussian process models for spatial and network autocorrelation. By using complete R code examples throughout, this book provides a practical foundation for performing statistical inference. Designed for both PhD students and seasoned professionals in the natural and social sciences, it prepares them for more advanced or specialized statistical modeling. Web Resource The book is accompanied by an R package (rethinking) that is available on the author's website and GitHub. The two core functions (map and map2stan) of this package allow a variety of statistical models to be constructed from standard model formulas.

Human-Robot Interaction Céline Jost, Brigitte Le Pévédic, Tony Belpaeme, Cindy Bethel, Dimitrios Chrysostomou, Nigel Crook, Marine Grandgeorge, Nicole Mirnig, 2020-05-13 This book offers the first comprehensive yet critical overview of methods used to evaluate interaction between humans and social robots. It reviews commonly used evaluation methods, and shows that they are not always suitable for this purpose. Using representative case studies, the book identifies good and bad practices for evaluating human-robot interactions and proposes new standardized processes as well as recommendations, carefully developed on the basis of intensive discussions between specialists in various HRI-related disciplines, e.g. psychology, ethology, ergonomics, sociology, ethnography, robotics, and computer science. The book is the result of a close, long-standing collaboration between the editors and the invited contributors, including, but not limited to, their inspiring discussions at the workshop on Evaluation Methods Standardization for Human-Robot Interaction (EMSHRI), which have been organized yearly since 2015. By highlighting and weighing good and bad practices in evaluation design for HRI, the book will stimulate the scientific community to search for better solutions, take advantages of interdisciplinary collaborations, and encourage the development of new standards to accommodate the growing presence of robots in the day-to-day and social lives of human beings.

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