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YVES HILPISCH

P EMBEDDED ROBOTICS THOMAS BRUNEL, 2008-09-20 This book presents a unique examination of mobile robots and embedded systems, from introductory to intermediate level. It is structured in three parts, dealing with embedded systems (hardware and software design, actuators, sensors, PID control, multitasking), mobile robot design (driving, balancing, walking, and flying robots), and mobile robot applications (mapping, robot soccer, genetic algorithms, neural networks, behavior-based systems, and simulation). The book is written as a text for courses in computer science, computer engineering, IT, electronic engineering, and mechatronics, as well as a guide for robot hobbyists and researchers.

P AUTOMATED MACHINE LEARNING FRANK HUTTER, LARS KOTTHOFF, JOAQUIN VANSCHOREN, 2019-05-17 This open access book presents the first comprehensive overview of general methods in automated machine learning (AutoML), collects descriptions of existing systems based on these methods, and discusses the first series of international challenges of AutoML systems. The recent success of commercial ML applications and the rapid growth of the field has created a high demand for off-the-shelf ML methods that can be used easily and without expert knowledge. However, many of the recent machine learning successes crucially rely on human experts, who manually select appropriate ML architectures (deep learning architectures or more traditional ML workflows) and their hyperparameters. To overcome this problem, the field of AutoML targets a progressive automation of machine learning, based on principles from optimization and machine learning itself. This book serves as a point of entry into this quickly-developing field for researchers and advanced students alike, as well as providing a reference for practitioners aiming to use AutoML in their work.

P AUTONOMOUS HORIZONS GREG ZACHARIAS, 2019-04-05 Dr. Greg Zacharias, former chief scientist of the United States Air Force (2015-18), explores next steps in autonomous systems (AS) development, fielding, and training. Rapid advances in AS development and artificial intelligence (AI) research will change how we think about machines, whether they are individual vehicle platforms or networked enterprises. The payoff will be considerable, affording the US military significant protection for aviators, greater effectiveness in employment, and unlimited opportunities for novel and disruptive concepts of operations. Autonomous Horizons: The Way Forward identifies issues and makes recommendations for the Air Force to take full advantage of this transformational technology.

P ADVANCES IN TELEROBOTICS MANUEL FERRE, MARTIN BUSS, RAFAEL ARACIL, CLAUDIO MELCHIORRI, CARLOS BALAGUER, 2007-08-10 A fascinating book that covers in detail all of the most recent advances in telerobotics. A must-read for scientists, researchers and students in teleoperation, it describes everything from methods and experimental results to applications and developments. Its three sections cover human system interfaces, control, and applications.

P TRANSPORT ROBOTIC SURGERY (TORS) GREGORY S. WEINSTEIN, BERT W. O'MALLEY, 2011-09-05

P NEWTON-EULER DYNAMICS MARK D. ARDEMA, 2006-10-28 Unlike other books on this subject, which tend to concentrate on 2-D dynamics, this text focuses on the application of Newton-Euler methods to complex, real-life 3-D dynamics problems. It is thus ideal for elective courses in intermediate dynamics.

P FIELD AND SERVICE ROBOTICS PETER CORKE, SALAH SUKKARIEH, 2006-08-03 The 5th International Conference on Field and Service Robotics (FSR05) was held in Port Douglas, Australia, on 29th - 31st July 2005, and brought together the worlds' leading experts in field and service automation. The goal of the conference was to report and encourage the latest research and practical results towards the use of field and service robotics in the community with particular focus on proven technology. The conference provided a forum for researchers, professionals and robot manufacturers to exchange up-to-date technical knowledge and experience. Field robots are robots which operate in outdoor, complex, and dynamic environments. Service robots are those that work closely with humans, with particular applications involving indoor and structured environments. There are a wide range of topics presented in this issue on field and service robots including: Agricultural and Forestry Robotics, Mining and Exploration Robots, Robots for Construction, Security & Defence Robots, Cleaning Robots, Autonomous Underwater Vehicles and Autonomous Flying Robots. This meeting was the fifth in the series and brings FSR back to Australia where it was first held. FSR has been held every 2 years, starting with Canberra 1997, followed by Pittsburgh 1999, Helsinki 2001 and Lake Yamanaka 2003.

P WORLD DEVELOPMENT REPORT 2019 WORLD BANK, 2018-10-31 Work is constantly reshaped by technological progress. New ways of production are adopted, markets expand, and societies evolve. But some changes provoke more attention than others, in part due to the vast uncertainty involved in making predictions about the future. The 2019 World Development Report will study how the nature of work is changing as a result of advances in technology today. Technological progress disrupts existing systems. A new social contract is needed to smooth the transition and guard against rising inequality. Significant investments in human capital throughout a person's lifecycle are vital to this effort. If workers are to stay competitive against machines they need to train or retool existing skills. A social protection system that includes a minimum basic level of protection for workers and citizens can complement new forms of employment. Improved private sector policies to encourage startup activity and competition can help countries compete in the digital age. Governments also need to ensure that firms pay their fair share of taxes, in part to fund this new social contract. The 2019 World Development Report presents an analysis of these issues based upon the available evidence.

P ROBOTS IN TRAVEL, TOURISM AND HOSPITALITY: KEY FINDINGS FROM A GLOBAL STUDY CRAIG WEBSTER, STANISLAV IVANOV, 2020-02-17 This report presents part of the results of the first global study on customers' perceptions on robots in travel, tourism, and hospitality implemented by the authors in 2018-2019. Specifically, the report presents the methodology of the research and elaborates on the key results regarding the activities that customers perceive as appropriate for robotisation, their preferences to be served by robots, and their willingness-to-pay for robot-delivered services. Finally, the report provides recommendations to travel, tourism, and hospitality companies how to implement successfully robotic technologies in their operations.

P PYTHON FOR FINANCE YVES HILPISCH, 2018-12-05 The financial industry has recently adopted Python at a tremendous rate, with some of the largest investment banks and hedge funds using it to build core trading and risk management systems. Updated for Python 3, the second edition of this hands-on book helps you get started with the language, guiding developers and quantitative analysts through Python libraries and tools for building financial applications and interactive financial analytics. Using practical examples throughout the book, author Yves Hilpisch also shows you how to develop a full-fledged framework for Monte Carlo simulation-based derivatives and risk analytics, based on a large, realistic case study. Much of the book uses interactive IPython notebooks.

P AGRICULTURAL ROBOTS JUN ZHOU, BAOHUA ZHANG, 2019-01-03 Over the past few decades, extensive research has been conducted on the applications of agricultural robots and automation to a variety of field and greenhouse operations, and technical fundamentals and their feasibility have also been widely demonstrated. Due to the unstructured environment, adverse interference and complicated and diversified operation process are the key of blocking its commercialization in robotic agricultural operations. Because of the development of automation techniques, smart sensors, and information techniques, some types of agricultural robots have achieved considerable success in recent years. This book intends to provide the reader with a comprehensive overview of the current state of the art in agricultural robots, fundamentals, and applications in robotic agricultural operations.

P THE DIGITAL FUNDRAISING BOOK MATT HOWARTH, CHARLOTTE TAYLOR, JORDAN HARLING, 2016-03-31 This is the guide for charities and nonprofits to help you learn all you need to know about digital fundraising. It covers everything from the very basics, right up to the tricky stuff, like maximising conversion rates. A must-read for anyone wanting to develop their digital fundraising strategy.

P THE ROBOTS' REBELLION - THE STORY OF SPIRITUAL RENAISSANCE DAVID ICKE, 1999-08-26 David Icke's strongest book to date, *The Robots' Rebellion* reveals the alarming extent to which people of all nations are programmed by the ideas fed to them by those in power. We live in a world which is increasingly dominated by technology but, according to Icke, it is we who are the robots. Fearlessly, he tears down the veils of hypocrisy, built up for generations by the corrupt forces of church, state, science and commerce — and reveals the true pathos of the human condition beneath. He points, too, to the frightening influence wielded throughout the planet by a merciless and manipulative network of secret societies. The existence of long-established links between Earth-bound humanity and beings from other dimensions and planets in the universe has been suppressed for years, says Icke, by the world's power-brokering hierarchy. When ordinary people learn the real role they have to play within a rich and varied cosmic society, rebellion against those who have kept this extraordinary truth from them will, he predicts, be inevitable. The author is no stranger to controversy. Formerly best-known as a TV sports commentator and leading spokesman for the British Green Party, he is gaining increasing authority as a tireless campaigner for truth. His widely-publicised spiritual transformation has given him the courage to speak out fearlessly against lies, deceit. Hidebound politicians, bankers, economists, educationalists, scientists and the leaders of the world's established religions are not going to welcome Icke's challenging book. But it is not intended for those who wield and abuse power. This book is for the world's unwilling robots who, says Icke, in an upbeat conclusion, have it within themselves to rise up — and take control of their own exciting destiny. *The Robots' Rebellion: Table of Contents* Introduction Remember Who You Are PART ONE: The Darkness - The Takeover Bid - Collective Amnesia - The Brotherhood of Clans - Bible Stories - Hell on Earth - Arabian Knights - The Cracks Appear - Eagle Tails - The Rule of Science - The World at War - Big is Beautiful - The New World Order - When Will We Ever Learn? PART TWO: The Light - Goodbye to All That - The Economics of Enough - The Politics of People - The Science of Sanity - Bricks in the Wall - Exploitation of the Spirit - The World Needs Rebels

P SHOCK WAVE-BOUNDARY-LAYER INTERACTIONS HOLGER BABINSKY, JOHN K. HARVEY, 2011-09-12 Shock wave-boundary-layer interaction (SBLI) is a fundamental phenomenon in gas dynamics that is observed in many practical situations, ranging from transonic aircraft wings to hypersonic vehicles and engines. SBLIs have the potential to pose serious problems in a flowfield; hence they often prove to be a critical - or even design limiting - issue for many aerospace applications. This is the first book devoted solely to a comprehensive, state-of-the-art explanation of this phenomenon. It includes a description of the basic fluid mechanics of SBLIs plus contributions from leading international experts who share their insight into their physics and the impact they have in practical flow situations. This book is for practitioners and graduate students in aerodynamics who wish to familiarize themselves with all aspects of SBLI flows. It is a valuable resource for specialists because it compiles experimental, computational and theoretical knowledge in one place.

P P2 - GAIN AND PASSIVITY TECHNIQUES IN NONLINEAR CONTROL ARJAN VAN DER SCHAFT, 2012-12-06 With respect to the first edition as Volume 218 in the Lecture Notes in Control and Information Sciences series the basic idea of the second edition has remained the same: to provide a compact presentation of some basic ideas in the classical theory of input-output and closed-loop stability, together with a choice of contributions to the recent theory of nonlinear robust and \mathcal{L} -FOO control and passivity-based control. Nevertheless, some parts of the book have been thoroughly revised and/or expanded, in order to have a more balanced presentation of

THE THEORY AND TO INCLUDE SOME OF THE NEW DEVELOPMENTS WHICH HAVE BEEN TAKEN PLACE SINCE THE APPEARANCE OF THE FIRST EDITION. I SOON REALIZED, HOW EVER, THAT IT IS NOT POSSIBLE TO GIVE A BROAD EXPOSITION OF THE EXISTING LITERATURE IN THIS AREA WITHOUT AFFECTING THE SPIRIT OF THE BOOK, WHICH IS PRECISELY AIMED AT A COMPACT PRESENTATION. SO AS A RESULT THE SECOND EDITION STILL REFLECTS VERY MUCH MY PERSONAL TASTE AND RESEARCH INTERESTS. I TRUST THAT OTHERS WILL WRITE BOOKS EMPHASIZING DIFFERENT ASPECTS. MAJOR CHANGES WITH RESPECT TO THE FIRST EDITION ARE THE FOLLOWING: • A NEW SECTION HAS BEEN ADDED IN CHAPTER 2 RELATING L2-GAIN AND PASSIVITY VIA SCATTERING, EMPHASIZING A COORDINATE-FREE, GEOMETRIC, TREATMENT. • THE SECTION ON STABILITY IN CHAPTER 3 HAS BEEN THOROUGHLY EXPANDED, ALSO INCORPORATING SOME RECENT RESULTS PRESENTED IN [182].

P NEURAL Network Control Of Robot Manipulators And Non-Linear Systems F W Lewis, S. Jagannathan, A Yesildirak, 2020-08-14 THERE HAS BEEN GREAT INTEREST IN UNIVERSAL CONTROLLERS THAT MIMIC THE FUNCTIONS OF HUMAN PROCESSES TO LEARN ABOUT THE SYSTEMS THEY ARE CONTROLLING ON-LINE SO THAT PERFORMANCE IMPROVES AUTOMATICALLY. NEURAL NETWORK CONTROLLERS ARE DERIVED FOR ROBOT MANIPULATORS IN A VARIETY OF APPLICATIONS INCLUDING POSITION CONTROL, FORCE CONTROL, LINK FLEXIBILITY STABILIZATION AND THE MANAGEMENT OF HIGH-FREQUENCY JOINT AND MOTOR DYNAMICS. THE FIRST CHAPTER PROVIDES A BACKGROUND ON NEURAL NETWORKS AND THE SECOND ON DYNAMICAL SYSTEMS AND CONTROL. CHAPTER THREE INTRODUCES THE ROBOT CONTROL PROBLEM AND STANDARD TECHNIQUES SUCH AS TORQUE, ADAPTIVE AND ROBUST CONTROL. SUBSEQUENT CHAPTERS GIVE DESIGN TECHNIQUES AND STABILITY PROOFS FOR NN CONTROLLERS FOR ROBOT ARMS, PRACTICAL ROBOTIC SYSTEMS WITH HIGH FREQUENCY VIBRATORY MODES, FORCE CONTROL AND A GENERAL CLASS OF NON-LINEAR SYSTEMS. THE LAST CHAPTERS ARE DEVOTED TO DISCRETE- TIME NN CONTROLLERS. THROUGHOUT THE TEXT, WORKED EXAMPLES ARE PROVIDED.

P MAINTENANCE AND Reliability Best Practices Ramesh Gulati, 2012-04 Drawing upon the authors many years of shop floor and management experience in a variety of industries, this

P COTTON Production Khawar Jabran, Bhagirath Singh Chauhan, 2019-08-05 Provides a comprehensive overview of the role of cotton in the economy and cotton production around the world. This book offers a complete look at the world's largest fiber crop: cotton. It examines its effect on the global economy—its uses and products, harvesting and processing, as well as the major challenges and their solutions, recent trends, and modern technologies involved in worldwide production of cotton. Cotton Production presents recent developments achieved by major cotton producing regions around the world, including China, India, USA, Pakistan, Turkey and Europe, South America, Central Asia, and Australia. In addition to origin and history, it discusses the recent advances in management practices, as well as the agronomic challenges and the solutions in the major cotton producing areas of the world. Keeping a focus on global context, the book provides sufficient details regarding the management of cotton crops. These details are not limited to the choice of cultivar, soil management, fertilizer and water management, pest control, cotton harvesting, and processing. The first book to cover all aspects of cotton production in a global context details the role of cotton in the economy, the uses and products of cotton, and its harvesting and processing. Discusses the current state of cotton management practices and issues within and around the world's cotton producing areas. Provides insight into the ways to improve cotton productivity in order to keep pace with the growing needs of an increasing population. Cotton Production is an essential book for students taking courses in agronomy and cropping systems as well as a reference for agricultural advisors, extension specialists, and professionals throughout the industry.

P SPEECH Enhancement Shoji Makino, Jingdong Chen, 2005-03-17 We live in a noisy world! In all applications (telecommunications, hands-free communications, recording, human-machine interfaces, etc) that require at least one microphone, the signal of interest is usually contaminated by noise and reverberation. As a result, the microphone signal has to be cleaned with digital signal processing tools before it is played out, transmitted, or stored. This book is about speech enhancement. Different well-known and state-of-the-art methods for noise reduction, with one or multiple microphones, are discussed. By speech enhancement, we mean not only noise reduction but also dereverberation and separation of independent signals. These topics are also covered in this book. However, the general emphasis is on noise reduction because of the large number of applications that can benefit from this technology. The goal of this book is to provide a strong reference for researchers, engineers, and graduate students who are interested in the problem of signal and speech enhancement. To do so, we invited well-known experts to contribute chapters covering the state of the art in this focused field.

P MULTI-ROBOT SYSTEMS: From SWARMS to INTELLIGENT AUTOMATA, VOLUME II Alan C. Schultz, Lynne E. Parker, Frank E. Schneider, 2010-12-08 This Proceedings Volume documents recent cutting-edge developments in multi-robot systems research and is the result of the Second International Workshop on Multi-Robot Systems that was held in March 2003 at the Naval Research Laboratory in Washington, D.C. This workshop brought together top researchers working in areas relevant to designing teams of autonomous vehicles, including robots and unmanned ground, air, surface, and undersea vehicles. The workshop focused on the challenging issues of team architectures, vehicle learning and adaptation, heterogeneous group control and cooperation, task selection, dynamic autonomy, mixed initiative, and human and robot team interaction. A broad range of applications of this technology are presented in this volume, including UCAVs (unmanned combat air vehicles), micro-air vehicles, UUVs (unmanned underwater vehicles), UGVs (unmanned ground vehicles), planetary exploration, assembly in space, clean-up, and urban search and rescue. This Proceedings Volume represents the contributions of the top researchers in this field and serves as a valuable tool for professionals in this interdisciplinary field.

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