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Yunhui Liu, Dong Sun

Build Your Own Paper Robots Julius Perdana, Josh Buczynski, Kurt Young, 2009-08-18 Presents projects, instructions, and color templates for fourteen paper robots.

Biologically Inspired Robotics Yunhui Liu, Dong Sun, 2011-12-21 Robotic engineering inspired by biology-biomimetics-has many potential applications: robot snakes can be used for rescue operations in disasters, snake-like endoscopes can be used in medical diagnosis, and artificial muscles can replace damaged muscles to recover the motor functions of human limbs. Conversely, the application of robotics technology to our understanding of biological systems and behaviors-biorobotic modeling and analysis-provides unique research opportunities: robotic manipulation technology with optical tweezers can be used to study the cell mechanics of human red blood cells, a surface electromyography sensing system can help us identify the relation between muscle forces and hand movements, and mathematical models of brain circuitry may help us understand how the cerebellum achieves movement control. Biologically Inspired Robotics contains cutting-edge material-considerably expanded and with additional analysis-from the 2009 IEEE International Conference on Robotics and Biomimetics (ROBIO). These 16 chapters cover both biomimetics and biorobotic modeling/analysis, taking readers through an exploration of biologically inspired robot design and control, micro/nano bio-robotic systems, biological measurement and actuation, and applications of robotics technology to biological problems. Contributors examine a wide range of topics, including: A method for controlling the motion of a robotic snake The design of a bionic fitness cycle inspired by the jaguar The use of autonomous robotic fish to detect pollution A noninvasive brain-activity scanning method using a hybrid sensor A rehabilitation system for recovering motor function in human hands after injury Human-like robotic eye and head movements in human-machine interactions A state-of-the-art resource for graduate students and researchers in the fields of control engineering, robotics, and biomedical engineering, this text helps readers understand the technology and principles in this emerging field.

Popular Science , 2005-09 Popular Science gives our readers the information and tools to improve their technology and their world. The core belief that Popular Science and our readers share: The future is going to be better, and science and technology are the driving forces that will help make it better.

Motion Planning for Humanoid Robots Kensuke Harada, Eiichi Yoshida, Kazuhito Yokoi, 2010-08-12 Research on humanoid robots has been mostly with the aim of developing robots that can replace humans in the performance of certain tasks. Motion planning for these robots can be quite difficult, due to their complex kinematics, dynamics and environment. It is consequently one of the key research topics in humanoid robotics research and the last few years have witnessed considerable progress in the field. Motion Planning for Humanoid Robots surveys the remarkable recent advancement in both the theoretical and the practical aspects of humanoid motion planning. Various motion planning frameworks are presented in Motion Planning for Humanoid Robots, including one for skill coordination and learning, and one for manipulating and grasping tasks. The problem of planning sequences of contacts that support acyclic motion in a highly constrained environment is addressed and a motion planner that enables a humanoid robot to push an object to a desired location on a cluttered table is described. The main areas of interest include: • whole body motion planning, • task planning, • biped gait planning, and • sensor feedback for motion planning. Torque-level control of multi-contact behavior, autonomous manipulation of moving obstacles, and movement control and planning architecture are also covered. Motion Planning for Humanoid Robots will help readers to understand the current research on humanoid motion planning. It is written for industrial engineers, advanced undergraduate and postgraduate students.

Vintage Paper Toys Franck Fries, 2015-09-07 Over the past few years, paper toys have made a major comeback! Simple, original and charming, they are now hugely popular worldwide. Children and adults alike can have fun making these French paper models of elegant automobiles, funny animals, and colorful characters. Make collections of the finished models, decorate your office or bedroom with them, or give them to friends and colleagues as gifts--Page 4 of cover.

Introduction to Mobile Robot Control Spyros G Tzafestas, 2013-10-03 Introduction to Mobile Robot Control provides a complete and concise study of modeling, control, and navigation methods for wheeled non-holonomic and omnidirectional mobile robots and manipulators. The book begins with a study of mobile robot drives and corresponding kinematic and dynamic models, and discusses the sensors used in mobile robotics. It then examines a variety of model-based, model-free, and vision-based controllers with unified proof of their stabilization and tracking performance, also addressing the problems of path, motion, and task planning, along with localization and mapping topics. The book provides a host of experimental results, a conceptual overview of systemic and software mobile robot control architectures, and a tour of the use of wheeled mobile robots and manipulators in industry and society. Introduction to Mobile Robot Control is an essential reference, and is also a textbook suitable as a supplement for many university robotics courses. It is accessible to all and can be used as a reference for professionals and researchers in the mobile robotics field. Clearly and authoritatively presents mobile robot concepts Richly illustrated throughout with figures and examples Key concepts demonstrated with a host of experimental and simulation examples No prior knowledge of the subject is required; each chapter commences with an introduction and background

Arduino Robotics John-David Warren, Josh Adams, Harald Molle, 2011-10-08 This book will show you how to use your Arduino to control a variety of different robots, while providing step-by-step instructions on the entire robot building process. You'll learn Arduino basics as well as the characteristics of different types of motors used in robotics. You also discover controller methods and failsafe methods, and learn how to apply them to your project. The book starts with basic robots and moves into more complex projects, including a GPS-enabled robot, a robotic lawn mower, a fighting bot, and even a DIY Segway-clone. Introduction to the Arduino and other components needed for robotics Learn how to build motor controllers Build bots from simple line-following and bump-sensor bots to more complex robots that can mow your lawn, do battle, or even take you for a ride Please note: the print version of this title is black & white; the eBook is full color.

Programming Robots with ROS Morgan Quigley, Brian Gerkey, William D. Smart, 2015-11-16 Chapter 3. Topics; Publishing to a Topic; Checking That Everything Works as Expected; Subscribing to a Topic; Checking That Everything Works as Expected; Latched Topics; Defining Your Own Message Types; Defining a New Message; Using Your New Message; When Should You Make a New Message Type?; Mixing Publishers and Subscribers; Summary; Chapter 4. Services; Defining a Service; Implementing a Service; Checking That Everything Works as Expected; Other Ways of Returning Values from a Service; Using a Service; Checking That Everything Works as Expected; Other Ways to Call Services; Summary.

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Human-Robot Interaction Christoph Bartneck, Tony Belpaeme, Friederike Eyssel, Takayuki Kanda, Merel Keijzers, Selma Šabanović, 2020-05-07 This broad overview for graduate students introduces multidisciplinary topics from robotics to sociology which are needed to understand the area.

Innovations in Applied Artificial Intelligence Bob Orchard, Chunsheng Yang, Ali Moonis, 2004-04-22 "Intelligent systems must perform in order to be in demand. " Intelligent systems technology is being applied steadily in solving many day-to-day problems. Each year the list of real-world deployed applications that inconspicuously host the results of research in the area grows considerably. These applications are having a significant impact in industrial operations, in financial circles, in transportation, in education, in medicine, in consumer products, in games and elsewhere. A set of selected papers presented at the seventeenth in the series of conferences on Industrial and Engineering Applications of Artificial Intelligence and Expert Systems (IEA/AIE 2004), sponsored by the International Society of Applied Intelligence, is offered in this manuscript. These papers highlight novel applications of the technology and show how new research could lead to new and innovative applications. We hope that you find these papers to be educational, useful in your own research, and stimulating. In addition, we have introduced some special sessions to emphasize a few areas of artificial intelligence (AI) that are either relatively new, have received considerable attention recently or perhaps have not yet been represented well. To this end, we have included special sessions on e-learning, bioinformatics, and human-robot interaction (HRI) to complement the usual offerings in areas such as data mining, machine learning, intelligent systems, neural networks, genetic algorithms, autonomous agents, natural language processing, intelligent user interfaces, evolutionary computing, fuzzy logic, computer vision and image processing, reasoning, heuristic search, security, Internet applications, constraint satisfaction problems, design, and expert systems.

Robotics B. Z. Sandler, 1999-04-28 Robotics, Second Edition is an essential addition to the toolbox of any engineer or hobbyist involved in the design of any type of robot or automated mechanical system. It is the only book available that takes the reader through a step-by step design process in this rapidly advancing specialty area of machine design. This book provides the professional engineer and student with important and detailed methods and examples of how to design the mechanical parts of robots and automated systems. Most robotics and automation books today emphasis the electrical and control aspects of design without any practical coverage of how to design and build the components, the machine or the system. The author draws on his years of industrial design experience to show the reader the design process by focusing on the real, physical parts of robots and automated systems. Answers the questions: How are machines built? How do they work? How does one best approach the design process for a specific machine? Thoroughly updated with new coverage of modern concepts and techniques, such as rapid modeling, automated assembly, parallel-driven robots and mechatronic systems Calculations for design completed with Mathematica which will help the reader through its ease of use, time-saving methods, solutions to

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Feedback Systems Karl Johan Åström, Richard M. Murray, 2021-02-02 The essential introduction to the principles and applications of feedback systems—now fully revised and expanded This textbook covers the mathematics needed to model, analyze, and design feedback systems. Now more user-friendly than ever, this revised and expanded edition of Feedback Systems is a one-volume resource for students and researchers in mathematics and engineering. It has applications across a range of disciplines that utilize feedback in physical, biological, information, and economic systems. Karl Åström and Richard Murray use techniques from physics, computer science, and operations research to introduce control-oriented modeling. They begin with state space tools for analysis and design, including stability of solutions, Lyapunov functions, reachability, state feedback observability, and estimators. The matrix exponential plays a central role in the analysis of linear control systems, allowing a concise development of many of the key concepts for this class of models. Åström and Murray then develop and explain tools in the frequency domain, including transfer functions, Nyquist analysis, PID control, frequency domain design, and robustness. Features a new chapter on design principles and tools, illustrating the types of problems that can be solved using feedback Includes a new chapter on fundamental limits and new material on the Routh-Hurwitz criterion and root locus plots Provides exercises at the end of every chapter Comes with an electronic solutions manual An ideal textbook for undergraduate and graduate students Indispensable for researchers seeking a self-contained resource on control theory

Karakuri Keisuke Saka, 2010-03-16 Japanese paper engineer Hosaka presents instructions for constructing four models: Tea-serving robot, Ready to fly, Peek-a-bear -- Wild Wild West.

Computer Vision in Control Systems-4 Margarita N. Favorskaya, Lakhmi C. Jain, 2018-09-01 The research book is a continuation of the authors' previous works, which are focused on recent advances in computer vision methodologies and technical solutions using conventional and intelligent paradigms. The book gathers selected contributions addressing a number of real-life applications including the identification of handwritten texts, watermarking techniques, simultaneous localization and mapping for mobile robots, motion control systems for mobile robots, analysis of indoor human activity, facial image quality assessment, android device controlling, processing medical images, clinical decision-making and foot progression angle detection. Given the tremendous interest among researchers in the development and applications of computer vision paradigms in the field of business, engineering, medicine, security and aviation, the book offers a timely guide for all PhD students, professors, researchers and software developers working in the areas of digital video processing and computer vision technologies.

Set My Heart to Five Simon Stephenson, 2020-09-01 Soon to be a major motion picture directed by Edgar Wright (Scott Pilgrim vs. the World): "Science fiction satire in the Vonnegut mold." —Cory Doctorow Set in a 2054 where humans have locked themselves out of the internet and Elon Musk has incinerated the moon, *Set My Heart to Five* is the hilarious yet profoundly moving story of one android's emotional awakening. One day at a screening of a classic movie, Jared notices a strange sensation around his eyes. Bots are not permitted to have feelings, but as the theater lights come on, Jared discovers he is crying. Soon overwhelmed by powerful emotions, Jared heads west, determined to find others like himself. But a bot with feelings is a dangerous proposition, and Jared's new life

could come to an end before it truly begins. Unless, that is, he can somehow change the world for himself and all of his kind. Unlike anything you have ever read before, *Set My Heart to Five* is a love letter to outsiders everywhere. Plus it comes uniquely guaranteed to make its readers weep a minimum of 29mls of tears.* *Book must be read in controlled laboratory conditions arranged at reader's own expense. Other terms and conditions may apply to this offer. "A beautiful, funny, heartfelt analysis of what it means to be human." –Simon Pegg "One of the most unique books ever crafted." –Mike Chen, New York Times–bestselling author "A funny, original, thought-provoking debut . . . It's wistful and sharp, particularly on what it really means to live." –Daily Mail

The Robotic Process Automation Handbook Tom Taulli, 2020-02-28 While Robotic Process Automation (RPA) has been around for about 20 years, it has hit an inflection point because of the convergence of cloud computing, big data and AI. This book shows you how to leverage RPA effectively in your company to automate repetitive and rules-based processes, such as scheduling, inputting/transferring data, cut and paste, filling out forms, and search. Using practical aspects of implementing the technology (based on case studies and industry best practices), you'll see how companies have been able to realize substantial ROI (Return On Investment) with their implementations, such as by lessening the need for hiring or outsourcing. By understanding the core concepts of RPA, you'll also see that the technology significantly increases compliance – leading to fewer issues with regulations – and minimizes costly errors. RPA software revenues have recently soared by over 60 percent, which is the fastest ramp in the tech industry, and they are expected to exceed \$1 billion by the end of 2019. It is generally seamless with legacy IT environments, making it easier for companies to pursue a strategy of digital transformation and can even be a gateway to AI. The Robotic Process Automation Handbook puts everything you need to know into one place to be a part of this wave. What You'll Learn Develop the right strategy and plan Deal with resistance and fears from employees Take an in-depth look at the leading RPA systems, including where they are most effective, the risks and the costs Evaluate an RPA system Who This Book Is For IT specialists and managers at mid-to-large companies

Generative Art Matt Pearson, 2011-06-29 Summary Generative Art presents both the technique and the beauty of algorithmic art. The book includes high-quality examples of generative art, along with the specific programmatic steps author and artist Matt Pearson followed to create each unique piece using the Processing programming language. About the Technology Artists have always explored new media, and computer-based artists are no exception. Generative art, a technique where the artist creates print or onscreen images by using computer algorithms, finds the artistic intersection of programming, computer graphics, and individual expression. The book includes a tutorial on Processing, an open source programming language and environment for people who want to create images, animations, and interactions. About the Book Generative Art presents both the techniques and the beauty of algorithmic art. In it, you'll find dozens of high-quality examples of generative art, along with the specific steps the author followed to create each unique piece using the Processing programming language. The book includes concise tutorials for each of the technical components required to create the book's images, and it offers countless suggestions for how you can combine and reuse the various techniques to create your own works. Purchase of the print book comes with an offer of a free PDF, ePub, and Kindle eBook from Manning. Also available is all code from the book. What's Inside The principles of algorithmic art A Processing language tutorial Using organic, pseudo-random, emergent, and fractal processes ===== Table of Contents Part 1 Creative Coding Generative Art: In Theory and Practice Processing: A Programming Language for Artists Part 2 Randomness and Noise The Wrong Way to Draw A Line The Wrong Way to Draw a Circle Adding Dimensions Part 3 Complexity Emergence Autonomy Fractals

ROS Robotics By Example Carol Fairchild, Dr. Thomas L. Harman, 2016-06-30 Bring life to your robot using ROS robotic applications About This Book This book will help you boost your knowledge of ROS and give you advanced practical experience you can apply to your ROS robot platforms This is the only book that offers you step-by-step instructions to solidify your ROS understanding and gain experience using ROS tools From eminent authors, this book offers you a plethora of fun-filled examples to make your own quadcopter, turtlebot, and two-armed robots Who This Book Is For If you are a robotics developer, whether a hobbyist, researchers or professional, and are interested in learning about ROS through a hands-on approach, then this book is for you. You are encouraged to have a working knowledge of GNU/Linux systems and Python. What You Will Learn Get to know the fundamentals of ROS and apply its concepts to real robot examples Control a mobile robot to navigate autonomously in an environment Model your robot designs using URDF and Xacro, and operate them in a ROS Gazebo simulation Control a 7 degree-of-freedom robot arm for visual servoing Fly a quadcopter to autonomous waypoints Gain working knowledge of ROS tools such as Gazebo, rviz, rqt, and Move-It Control robots with mobile devices and controller boards In Detail The visionaries who created ROS developed a framework for robotics centered on the commonality of robotic systems and exploited this commonality in ROS to expedite the development of future robotic systems. From the fundamental concepts to advanced practical experience, this book will provide you with an incremental knowledge of the ROS framework, the backbone of the robotics evolution. ROS standardizes many layers of robotics functionality from low-level device drivers to process control to message passing to software package management. This book provides step-by-step examples of mobile, armed, and flying robots, describing the ROS implementation as the basic model for other robots of these types. By controlling these robots, whether in simulation or in reality, you will use ROS to drive, move, and fly robots using ROS control. Style and approach This is an easy-to-follow guide with hands-on examples of ROS robots, both real and in simulation.

Applications of Robotics in Industry Using Advanced Mechanisms Janmenjoy Nayak, Valentina E. Balas, Margarita N. Favorskaya, Bibhuti Bhusan Choudhury, S. Krishna Mohan Rao, Bighnaraj Naik, 2019-09-03 This book shares important findings on the application of robotics in industry using advanced mechanisms, including software and hardware. It presents a collection of recent trends and research on various advanced computing paradigms such as soft computing, robotics, smart automation, power control, and uncertainty analysis. The book constitutes the proceedings of the 1st International Conference on Application of Robotics in Industry using Advanced Mechanisms (ARIAM2019), which offered a platform for sharing original research findings, presenting innovative ideas and applications, and comparing notes on various aspects of robotics. The contributions highlight the latest research and industrial applications of robotics, and discuss approaches to improving the smooth functioning of industries. Moreover, they focus on designing solutions for complex engineering problems and designing system components or processes to meet specific needs, with due considerations for public health and safety, including cultural, societal, and environmental considerations. Taken together, they offer a valuable resource for researchers, scientists, engineers, professionals and students alike.

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